

Amplitude (A) is the maximum displacement of the oscillator from the equilibrium position.

Example: On average a human heart is found to beat 75 times in a minute. Calculate its frequency and period.

$$\Rightarrow f = \frac{75}{1 \text{ minute}} = \frac{75}{60 \text{ s}} = \underline{\underline{1.25 \text{ Hz}}}$$

$$T = \frac{1}{f} = \frac{1}{1.25 \text{ Hz}} = \underline{\underline{0.8 \text{ Sec}}}$$

→ Simple harmonic motion is a special type of oscillatory motion caused by a restoring force which obeys Hooke's law.

In SHM acceleration

a) is always directly proportional in size but opposite in direction to its displacement (x).

A block of mass m , attached to one end of a spring, of constant k and oscillating in a horizontal frictionless floor, is example of SHM.



$$F_s = -kx$$

The minus (-) sign shows the force is always acting opposite to the displacement and always tries to restore the block back to its equilibrium position.

Newton's 2nd law $F_s = ma$

$$ma = -kx \rightarrow a = -\left(\frac{k}{m}\right)x = \underline{\underline{-\omega^2 x}}$$

* K is Constant of proportionality called the Spring Constant or Stiffness factor and ω is angular frequency of oscillator.

Characteristics of SHM

- 1) The amplitude A is constant
- 2) The frequency and period are independent of Amplitude
3. The fluctuating quantity can be expressed in terms of Sinusoidal function of a Single frequency.

For SHM to occur

- there must be a stable equilibrium position
- there must be no dissipation of energy
- the acceleration is proportional to displacement & opposite in direction.

Displacement, Velocity and acceleration in SHM

① Displacement $\rightarrow X = A \sin \omega t$

$$\textcircled{a} \quad \text{Velocity} = wA \cos(\omega t)$$

$$\textcircled{1} \text{ Acceleration} = -\omega^2 A \sin(\omega t) = -\omega^2 X$$

* Maximum Velocity occurs at equilibrium position with zero displacement.

* Maximum acceleration occurs at $X = \pm A$; $a_{\max} = \omega^2 A$

$$V_{max} = \omega A$$

Example

An object oscillates with SHM along x-axis. its position Varies with time according to equation $x = (4.00) \text{m} \cos(\pi t + \frac{\pi}{4})$ where t is in seconds and angles in radians.

- Determine A , f , and T of motion
 - Calculate \vec{V} , & \vec{a} at any time.
 - Using results of part b, determine position, Velocity & \vec{a} at $t = 15$
 - determine maximum Speed and maximum acceleration of object.

Solution

Guler

Given $x = (4.00) \text{ m} \cos(\pi t + \frac{\pi}{4})$ with the general eqn of Simple HM

$$a) A = 4m, \omega = \underline{\pi_{rad}}$$

$$x(t) = A \cos(\omega t + \phi)$$

$$T = \frac{1}{f} = \frac{1}{0.5} = 2 \text{ sec}$$

$$b) \vec{V} = \frac{dx}{dt} = \frac{d(4m \cos(\omega t + \frac{\pi}{4}))}{dt} = - (4\pi)m/\text{sin}(\omega t + \frac{\pi}{4})$$

$$a = \frac{dv}{dt} = - (4\pi)^2 m/s^2 \cos(\pi t + \frac{\pi}{4})$$

c) at $t = 1.5$ sec

$$x(t) = 4 \cos(\pi t + \frac{\pi}{4}) = 4 \cos(\pi(u) + \frac{\pi}{4})$$

$$V(t) = -4\pi \sin(\pi t + \frac{\pi}{4}) = 4 \cos(\pi t + \frac{\pi}{4}) = -2.83 \text{ m}$$

$$= -4 \times \sin \frac{5\pi}{4} = 8.89 \text{ m/s}$$

$$a(t) = - (4\pi)^2 \cos(\pi(t) + \pi_0)$$

$$d) V_{max} = \omega A = 12.56 \text{ m/s}$$

$$a_{\max} = \omega^2 A = 39.4 \text{ m/s}^2$$

The Concept of Heat, Work and Internal energy

Heat, Symbol Q and Unit Joule(J) is spontaneous flow of energy into or out of a system caused by adiabatic temperature b/w system and surroundings.

Work, Symbol W and Unit Joule(J), is non-spontaneous energy transfer into or out of a system due to force acting through a displacement.

Work takes many forms, moving a piston or stirrer or running an electrical current through resistance.

Work is the non-spontaneous transfer of energy. Heat is microscopic form of energy transfer, involving large no of particles.

A System Cannot possess heat or work. These two are energies that flow into or Out of a system.

Heat transfer Obey's the law of Conservation of energy (if no heat is lost to surroundings)

$$Q_{\text{lost by hotter object}} = Q_{\text{gained by cooler object}}$$

Internal Energy, symbol U, is defined as the energy associated with the random, disordered motion of the microscopic components-atoms and molecules.

Specific Heat and Latent Heat

Specific heats:

Heat flowing into or out of a body (or system) changes the temperature of the body (or system) except during phase changes the temperature remains constant.

→ The quantity of heat Q required to change the temperature of the body of mass m by ΔT is proportional to both mass & ΔT

$$\text{Mathematically } Q \propto m \Delta T \rightarrow Q = mc \Delta T \quad \begin{matrix} c - \text{heat capacity} \\ (\text{or specific heat}) \end{matrix}$$

C- the amount of heat required to raise temperature of unit mass of any substance through a unit degree.

SI unit is J/kg-K or J/kg.°C

→ The amount of heat required to change the temperature of n moles of a substance is $Q = n c \Delta T$

Latent heats:

Latent heat is the heat required per unit mass of a substance to produce a phase change at constant temperature.

→ the latent heat, Q_L , required to change the phase of "m" mass of a body at constant temperature is

Types of latent heats

$$Q_L = \pm mL$$

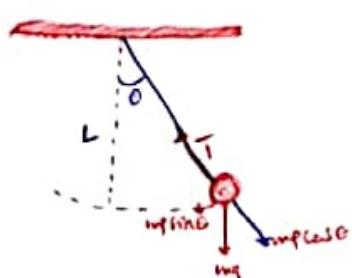
L-Specific latent heat required to change a phase of 1kg of a substance at a constant temperature.

1) Latent heat of fusion (L_f) is the heat absorbed or released when matter melts changing phase from solid to liquid form at constant temperature.

2) Latent heat of vaporization (L_v) is the heat absorbed or released when matter vaporizes changing phase from liquid to gas phase at constant temperature

The Simple Pendulum

A simple pendulum is another mechanical system that exhibits periodic motion.



The force of gravity is the only force that acts on the pendulum.

The pendulum bob moves along a circular arc, rather than back and forth in a straight line.

$$\text{Hooke's law} \rightarrow T = 2\pi \sqrt{\frac{L}{g}}$$

L-length
g-gravity
T-period

- * Period of simple pendulum does not depend on mass but only length & free fall acceleration.

Eg. A rock swings in a circle constant speed on the end of a string, making 50 revolutions in 30 sec. What is frequency and period of this motion?

Soln $f = \frac{50 \text{ rev}}{30 \text{ sec}} = 1.67 \text{ rev/sec} = 1.67 \text{ Hz}$

$$T = \frac{1}{f} = \frac{1}{1.67} = 0.6 \text{ sec}$$

Energy of Simple Harmonic Oscillator

In the absence of friction, the total energy of a block-spring system is constant and equal to the sum of kinetic and potential energies.

$$PE = \frac{1}{2} kx^2 \quad KE = \frac{1}{2} mv^2$$

∴ Total energy of the oscillator performing SHM is

$$E = \frac{1}{2} KA^2$$

- * Energy of SHM is constant & proportional to square of Amplitude.

Wave and Its Characteristics

- * Wave is a disturbance from normal or equilibrium conditions that travels, or propagates, carrying energy and momentum through space without the transport of matter.

- * Pulse is a single disturbance travelling into a medium.

Wave supplies energy to the particles in a medium to set them in motion.

Terminologies in Wave

Crests / Thoughts: are positions in a wave with maximum displacement above/below the equilibrium position.

Amplitude (A) :- is the maximum displacement from equilibrium position.

Displacement (y) :- is position of a wave from equilibrium position at any time.

Example 3

How much heat energy is required to change a dog's ice cube from a solid at -10°C to steam at 110°C .

Solution

To raise the temperature of the ice to 0°C we need

$$\Delta Q_{\text{ice}} = m_{\text{ice}} C_{\text{ice}} \Delta T = 0.04 \text{ kg} \left(0.49 \frac{\text{kcal}}{\text{kg} \cdot ^\circ\text{C}} \right) 10^{\circ}\text{C}$$

To melt the ice we need $= \underline{\underline{0.196 \text{ kcal}}}$

$$\Delta Q_{\text{ice}} = m_{\text{ice}} L_{\text{ice}} = 0.04 \text{ kg} (30 \text{ kcal/kg}) = \underline{\underline{3.2 \text{ kcal}}}$$

To raise the temperature of 106°C we need

$$\Delta Q_{\text{ice}} = m_{\text{water}} C_{\text{water}} \Delta T = 0.04 \text{ kg} \left(1 \frac{\text{kcal}}{\text{kg} \cdot ^\circ\text{C}} \right) 100^{\circ}\text{C} = \underline{\underline{4 \text{ kcal}}}$$

To raise the temperature of the system to 110°C we need

$$\Delta Q_{\text{ice}} = m_{\text{system}} C_{\text{system}} \Delta T = 0.4 \text{ kg} (0.48 \text{ kcal}/(\text{kg} \cdot ^\circ\text{C})) [10^{\circ}\text{C}] = \underline{\underline{0.192 \text{ kcal}}}$$

To boil the water need

$$\Delta Q_{\text{L}} = m_{\text{water}} L_{\text{water}} = 0.04 \text{ kg} (540 \text{ kJ/kg}) = \underline{\underline{21.6 \text{ kJ}}}$$

Therefore total heat energy required is

$$\Delta Q = (0.96 + 3.2 + 4 + 21.6 + 0.192) \text{ kcal} = \underline{\underline{29.182 \text{ kcal}}}$$

Ex 2 If 90g of molten lead at 327.3°C is poured into a 30g Casting form made of iron and initially at 20°C . What is the final ~~for~~ temperature of the system?
Assume no energy loss to env't.

Soln The melting point of lead is 327.3°C . Assume the final temperature of the system is T .

* The amount of energy released by the lead as it solidifies is

$$\Delta Q_{\text{L}} = m_{\text{lead}} L_{\text{lead}} = 0.09 \text{ kg} (2.45 \times 10^4 \text{ J/kg}) = \underline{\underline{2205 \text{ J}}}$$

* The amount of energy released as it cools is

$$\Delta Q = m_{\text{lead}} C_{\text{lead}} \Delta T = 0.09 (128) (327.3 - T) = (11.52) (327.3 - T)$$

The energy is absorbed by the iron, for the iron

$$2205 + (11.52) (327.3 - T) = m_{\text{iron}} C_{\text{iron}} \Delta T = 0.3 (448) (T - 20)$$

$$5595.5 - (11.52) T = 134T - 2688$$

$$8663.5 = 145.52T$$

$$T = 59.5^{\circ}\text{C}$$

Example-1

5000J of heat are added to two moles of an ideal monatomic gas, initially at a temperature of 500K, while the gas performs 7500J of work. What is the final temperature of the gas?

Solution

$$\begin{aligned}\Delta U &= Q + W \\ &= 5000 - 7500 \\ &= -2500 \text{ J}\end{aligned}$$

$$\text{from equation } \Delta U = nC\Delta T \rightarrow \Delta U = \frac{3}{2}nR\Delta T$$

$$\Delta U = \frac{3}{2}nR\Delta T$$

$$-2500 = \frac{3}{2}(2)(8.31) \Delta T$$

$$\underline{\underline{\Delta T = -100 \text{ K}}}$$

$$\begin{aligned}\Delta T &= T_f - T_i \\ -100 \text{ K} &= T_f - 500 \text{ K}\end{aligned}$$

$$\underline{\underline{T_f = 400 \text{ K}}}$$

Example-2

2000J of heat leaves the system and 2500J of work is done on the system.

What is the change in internal energy of the sys?

Soln

$$Q = -2000 \text{ J}$$

$$\underline{\underline{W = 2500 \text{ J}}}$$

$$\Delta U = Q + W$$

$$= -2000 + 2500$$

$$\boxed{\Delta U = 500 \text{ J}}$$

Activity: A 1 mol sample of an ideal gas is kept at 0.0°C during an expansion from 3.0L to 10L

a) How much work is done on the gas during expansion?

Solution

$$W = nRT \ln\left(\frac{V_f}{V_i}\right)$$

$$= (1 \text{ mol}) (8.315 \text{ J/mol.K}) (273 \text{ K}) \ln\left(\frac{10}{3}\right)$$

$$= 0.73 \times 10^3 \text{ J}$$

b) How much energy transferred by heat occurs with the surroundings in this process

$$\Delta U = Q + W$$

~~$\Delta U = 0$~~

$$Q = W$$

$$\underline{\underline{Q}}$$

$$\underline{\underline{Q = W = 0.73 \times 10^3 \text{ J}}}$$

Bernoulli's Equation

- * The sum of pressure, kinetic energy per unit volume, and gravitational potential energy per unit volume has the same value at all points along a streamline.

(This is called Bernoulli's Equation)

$$P_1 + \frac{1}{2} \rho V_1^2 + \rho g h_1 = P_2 + \frac{1}{2} \rho V_2^2 + \rho g h_2$$

ρ = density
 V = Velocity
 P = pressure

Example

Water circulates throughout a house in a hot water heating system. If the water is pumped at a speed of 0.50 m/s through a 4 cm diameter pipe in basement under pressure of 3.03×10^5 Pa. What will be velocity and pressure in a 2.6 cm diameter pipe on the 2nd floor 5m above?

Given

$$V_1 = 0.5 \text{ m/s} \quad V_2 = ?$$

$$h_1 = 0 \text{ m (horizontal)} \quad h_2 = 5 \text{ m}$$

$$d_1 = 4 \text{ cm} = 0.04 \text{ m} \quad d_2 = 2.6 \text{ cm} = 0.026 \text{ m}$$

$$A_1 = \pi r_1^2 = \pi (d_1/2)^2 \quad A_2 = \pi (d_2/2)^2 = \underline{\underline{1.69 \times 10^{-4} \pi}}$$

$$= \underline{\underline{0.0004 \pi}}$$

$$P_1 = 3.03 \times 10^5 \text{ Pa} \quad P_2 = ?$$

Solution

from Equation of Continuity

$$A_1 V_1 = A_2 V_2$$

$$V_2 = \frac{A_1 V_1}{A_2} = \frac{(0.0004 \pi)(0.5)}{1.69 \times 10^{-4} \pi} = \underline{\underline{11.83 \text{ m/s}}}$$

from Bernoulli's Equation

$$\begin{aligned} P_2 &= P_1 + \frac{1}{2} \rho V_1^2 + \rho g h_1 - \frac{1}{2} \rho V_2^2 - \rho g h_2 \\ &= P_1 + \frac{1}{2} \rho (V_1^2 - V_2^2) + \rho g (h_1 - h_2) \\ &= 3.03 \times 10^5 + \frac{1}{2} (1.0 \times 10^3) [0.5^2 - 11.83^2] + (1 \times 10^3) (9.8) [0 - 5] \end{aligned}$$

$$\underline{\underline{P_2 = 1.84 \times 10^5 \text{ Pa}}}$$

The first law of thermodynamics

The 1st law of thermodynamics states that "The change in internal energy of a system is equal to the sum of the heat flow into the system and the work done on the system." In equation $\Delta U = Q + W$

ΔU - change in internal energy

$W = P\Delta V$ - Work done on the system

- P - Pressure

- ΔV - Volume

The first law of different thermodynamic sys

Isolated System :- is a system which does not exchange heat with its surroundings and no work is done on the external environment.

$$\boxed{\Delta U = 0 \text{ or } U = \text{constant}} \quad \begin{array}{l} \text{The internal energy of an isolated system} \\ \text{is constant.} \end{array}$$

Cyclic process :- Engines Operate in Cycles, in which the system, Example, gas periodically returns to its initial state.

Since, the system returns to its initial state, the change in internal energy in one complete cycle is zero.

$$\Delta U = 0 \rightarrow \text{So, } Q = W$$

Isochoric process :- In a constant volume process, the volume of the system stays constant.

$$\text{Consequently, } W = 0 \rightarrow \Delta U = Q$$

\rightarrow All the heat entering the system goes into increasing internal energy

Adiabatic process :- The System does not exchange heat with its surroundings, $Q = 0 \rightarrow \Delta U = W$

Isothermal process :- It is a process which involves no change in temperature of the system.

If the process occurs at constant temperature then there is no change in the internal energy of the system so ΔU .

The 1st law for isothermal

$$\Delta U = Q + W \rightarrow 0 = Q + W$$

For ideal gas in isothermal process

$$\boxed{Q = -W}$$

$$\boxed{W = nRT \ln \left(\frac{V_f}{V_i} \right)}$$

Isochoric process :- the expansion or compression occurs at constant pressure. Any work done by the system will result in an increase in volume

\curvearrowleft The work done on pressure-volume graph is equal to under PV graph area

$$\text{For isochoric } W = P\Delta V = P(V_f - V_i)$$

$$\text{jst law of isochoric process} \rightarrow \Delta U = Q + W \text{ or } \boxed{\Delta U = Q - P\Delta V}$$

$$= Q - P(V_f - V_i)$$

CHAPTER-5

Simple Harmonic Motion

5.1.1 Periodic and Oscillatory Motion

When a body repeats its path of motion back and forth about the equilibrium or mean position, the motion is said to be periodic.

Types of Oscillatory motion

There are two types of oscillatory motion

Linear oscillation &
Circular oscillation

Example of Linear oscillation

1. Oscillation of mass spring system
2. Oscillation of fluid column in U-tube
3. Oscillation of floating cylinder
4. Oscillation of body dropped in a tunnel along earth diameter.
5. Oscillation of strings of musical instruments.

Example of Circular motion

1. Oscillation of simple pendulum
2. Oscillation of solid sphere in a cylinder
3. Oscillation of circular ring suspended in air
4. Oscillation of balance wheel of a clock
5. Rotation of earth around the Sun

Oscillatory System

Oscillations are the basic blocks of waves. Oscillatory systems are of two types mechanical and non-mechanical systems.

Mechanical Oscillatory Systems :- in this type of a system a body itself changes its position. For mechanical oscillation two things are especially responsible, inertia and restoring force.

Non-mechanical Oscillatory Systems :- the body itself doesn't change its position but its physical property varies periodically.

Period $\rightarrow (T)$:- is the time required to complete one full cycle of vibration or oscillation.

Frequency $\rightarrow (f)$:- The frequency is the number of complete oscillations or cycles per unit time.

The frequency of wave is given by
$$f = \frac{1}{T}$$

Chapter Questions and problems

1. A 200kN load is hung on a wire having a length of 4.00m, cross-sectional area $0.2 \times 10^{-4} m^2$ and Young Modulus $8 \times 10^{10} N/m^2$ what is increase in length?

Given

$$l_0 = 4 \text{ m}$$

$$A = 0.2 \times 10^{-4} m^2$$

$$Y = 8 \times 10^{10} N/m^2$$

$$m = 200 \text{ kg}$$

$$\Delta l = ?$$

From Young Modulus

$$Y = \frac{F_2}{A} = \frac{F_2 l_0}{\frac{\Delta l}{l_0}} = \frac{F_2 l_0}{\Delta l l_0}$$

$$F_2 = mg$$

Sol.

$$\Delta l = \frac{F_2 l_0}{A Y} = \frac{mg l_0}{A Y}$$

Answer

$$\underline{\underline{\Delta l = 4.91 \text{ mm}}}$$

$$\Delta l = \frac{200 \text{ kN} (9.8 \text{ m/s}^2) (4 \text{ m})}{0.2 \times 10^{-4} m^2 \times 8 \times 10^{10} N/m} \approx \underline{\underline{4.91 \text{ mm}}}$$

2. A steel wire of diameter 1mm can support a tension of 0.2kN. A steel cable to support a tension of 20kN should have diameter of what order of magnitude?

From Young modulus

$$Y = \frac{F_2 l_0}{\Delta l A} \rightarrow A = \frac{F_2 l_0}{\Delta l Y}$$

Given $d_1 = 1 \text{ mm}$

$$F_1 = 0.2 \text{ kN}$$

$$F_2 = 20 \text{ kN}$$

$$d_2 = ?$$

Let A_1 - Cross-sectional Area of steel wire
 A_2 - $\dots \dots \dots$ of steel cable

$$A_1 = \frac{F_2 l_0}{Y d_1} \quad A_2 = \frac{F_2 l_0}{Y d_2} \xrightarrow{\text{So,}} \frac{A_2}{A_1} = \frac{\frac{F_2 l_0}{Y d_2}}{\frac{F_2 l_0}{Y d_1}} = \frac{d_1}{d_2}$$

$$\frac{A_2}{A_1} = \frac{F_2}{F_1}$$

$$A_1 = \frac{\pi d_1^2}{4}$$

$$A_2 = \frac{\pi d_2^2}{4}$$

$$\frac{\frac{\pi d_2^2}{4}}{\frac{\pi d_1^2}{4}} = \frac{F_2}{F_1} \rightarrow \frac{d_2^2}{d_1^2} = \frac{F_2}{F_1}$$

$$d_2^2 = d_1^2 \times \frac{F_2}{F_1}$$

$$d_2^2 = (1 \times 10^{-3} \text{ m})^2 \times \frac{20 \text{ kN}}{0.2 \text{ kN}} = 10^{-6} \times 100 = \underline{\underline{10^{-4}}}$$

$$d_2 = \sqrt{10^{-4} \text{ m}^2} = \underline{\underline{10^{-2} \text{ m}}}$$

$$d_2 = \underline{\underline{10 \text{ mm}}}$$

3. A 30 kg hammer strikes a steel spike 2.30 cm in diameter. Spike 2.30 cm in diameter while moving with a speed of 20 m/s. The hammer rebounds with speed 10 m/s after impact. What is the average strain in the spike during impact?

Given

$$\begin{aligned}m &= 30 \text{ kg} \\ \Delta t &= 0.11 \text{ s}\end{aligned}$$

$$V_i = 20 \text{ m/s}$$

$$V_f = -10 \text{ m/s} \text{ (rebounded)}$$

$$\text{Strain} = ?$$

Solution

$$\text{Stress} = \frac{F}{A}$$

$$\text{Impulse} = \Delta P$$

$$F \cdot \Delta t = m(V_f - V_i)$$

$$F \times 0.11 = 30 (-10 - 20)$$

$$F = \frac{-900}{0.11} = \underline{\underline{8.18 \times 10^3 \text{ N}}}$$

$$\text{Stress} = \frac{8.18 \times 10^3 \text{ N}}{\pi \times \left(\frac{2.3}{2} \times 10^{-2}\right)^2}$$

$$A = \pi \left(\frac{d}{2}\right)^2 = \pi \left(\frac{2.3}{2} \times 10^{-2}\right)^2$$

$$\boxed{\text{Stress} = 1.97 \times 10^7 \text{ N/m}^2}$$

$$\text{Strain} = \frac{\text{Stress}}{\gamma} = \frac{1.97 \times 10^7}{2 \times 10^{-11}} = \underline{\underline{9.85 \times 10^{-5}}}$$

4. If the shear stress in steel exceeds about $4 \times 10^8 \text{ N/m}^2$, the steel ruptures. Determine the shearing force necessary to

a) shear a steel bolt 1 cm in diameter

b) punch a 1 cm diameter hole in a steel plate 0.5 cm thick

Solution

a) Stress = $\frac{F}{A} \rightarrow \boxed{\text{Force applied} = \text{Stress} \times \text{Area}}$

$$F = 4 \times 10^8 \text{ N/m}^2 \times \pi r^2$$

$$r = \frac{d}{2} = \frac{1}{2} = 0.5 \text{ cm}$$

$$= 4 \times 10^8 \text{ N/m}^2 \times \pi (0.5 \times 10^{-2})^2$$

$$r = \underline{\underline{5 \times 10^{-3} \text{ m}}}$$

$$= \underline{\underline{3.14 \times 10^4 \text{ N}}}$$

b) The area over which shear stress occurs is equal to the circumference of the hole times its thickness

$$\text{Thus, } A = (2\pi r)t = 2\pi (0.5 \times 10^{-2} \text{ m}) (0.5 \times 10^{-2} \text{ m}) = \underline{\underline{1.57 \times 10^{-4} \text{ m}^2}}$$

$$\therefore F = A \times \text{stress}$$

$$= (1.57 \times 10^{-4} \text{ m}^2) (4 \times 10^8 \text{ N/m}^2)$$

$$\boxed{F = 6.28 \times 10^4 \text{ N}}$$

CHAPTER - 4

HEAT AND THERMODYNAMICS

Thermodynamics is a science of the relationship b/w heat, work, temperature & energy.
It deals with the transfer of energy from one system to another / from one form to other.

Heat is defined as the flow of energy from one object to another. This flow of energy is caused by a difference in T° . Heat can flow \rightarrow if they are in thermal contact.

Two objects are in thermal equilibrium if they are in close contact that allows either to gain energy from other, but nevertheless no energy transferred.

Experimentally, if object A is in thermal equilibrium with object B, and object B is in thermal equilibrium with object C, then, object A is in thermal equilibrium with object C. \rightarrow This is called the Zeroth law of thermodynamics.

* Thermometers measure Temperature according to well-defined scales of measurement
The three most common T° -scales are Fahrenheit, Celsius and Kelvin.

\rightarrow Temperature scales are created by identifying two reproducible temperatures
The freezing and boiling T° of water at standard atmospheric pressure used.

* Freezing point of water is 0°C and boiling point is 100°C . [degree Celsius]

* Freezing point of water is 32°F and boiling point is 212°F (degree Fahrenheit)

$$* T_F = \frac{5}{9} T_C + 32$$

$$T_K = \frac{5}{9} (T_F - 32) + 273.15$$

$$* T_C = \frac{9}{5} (T_F - 32)$$

$$T_F = \frac{9}{5} (T_C - 273.15) + 32$$

$$* T_K = T_C + 273.15$$

Thermal Expansion

Thermal expansion is the change in size or volume of a given system as its temperature changes. Example Expansion of alcohol, expansion of air

\rightarrow Linear thermal expansion

The increase in length Δl of a solid is proportional to its initial length, l_0 and the change in its temperature ΔT . The proportionality constant is called the coefficient of linear expansion α .

$$\boxed{\Delta l = \alpha l_0 \Delta T} \rightarrow l = l_0 (1 + \alpha \Delta T) \quad \alpha = \frac{l_0}{\Delta l} \Delta T$$

\rightarrow Areal Expansion

$$\Delta A = \beta A_0 \Delta T \Rightarrow A = A_0 (1 + \beta \Delta T) \rightarrow \boxed{\beta = 2\alpha} \quad \text{it has units } \text{K}^{-1}$$

\rightarrow Volume Expansion

$$\boxed{\beta = 3\alpha} \quad \text{coefficient and } (C^\circ)^{-1}$$

9) calculate the absolute pressure at an ocean depth of 1.0×10^3 m. Assume that the density of the water is $1.025 \times 10^3 \text{ kg/m}^3$ and that $P_{atm} = 1.01 \times 10^5 \text{ Pa}$

Solution

Given

$$h = 1.0 \times 10^3 \text{ m}$$

$$\rho_w = 1.025 \times 10^3 \text{ kg/m}^3$$

$$P_{atm} \text{ or } P_0 = 1.01 \times 10^5 \text{ Pa}$$

$$P_{absolute} = ?$$

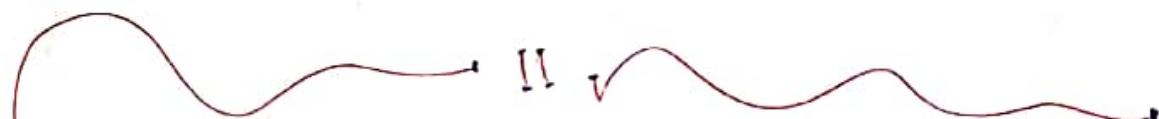
Soln

$$P_{abs} = P_{gauge} + P_{atm}$$

$$= \rho g h + P_{atm}$$

$$= (1.025 \times 10^3 \text{ kg/m}^3) (9.81 \text{ m/s}^2) (1 \times 10^3 \text{ m}) + 1.01 \times 10^5 \text{ Pa}$$

$$\underline{\underline{P_{absolute} = 1.01 \times 10^7 \text{ Pa}}}$$



!!

END OF CH-3

5) Lead has a greater density than iron, and both are denser than water. Is the buoyant force on a lead object greater than, less than or equal to the buoyant force on an iron object of the same volume?

Solution The buoyant force of a liquid on an object is equal to the weight of liquid displaced by it.

⇒ since the lead object and iron object have the same volume, both of them displace the same amount of water. Hence buoyant force is the same.

6. When an object is immersed in a liquid at rest, why is the net force on an object in the horizontal direction is equal to zero?

Solution The pressure is the same on points that are at the same level but on opposite sides, so net force along horizontal equals to zero.

7. When water freezes, it expands by about 9.0%. What pressure increase would occur inside your automobile engine block if the water in it froze? (The bulk modulus of ice is $2 \times 10^9 \text{ N/m}^2$)

Solution

$$B = \frac{\Delta P}{\Delta V/V} \rightarrow \Delta P = B \times \frac{\Delta V}{V}$$

Given

$$\Delta V = 9\% V$$

$$\boxed{\Delta V = 0.09 V}$$

$$V_c = V$$

$$= [2 \times 10^9 \text{ N/m}^2] \times \left(\frac{0.09 V}{V} \right)$$

$$\Delta P = 0.18 \times 10^9 \text{ N/m}^2$$

$$\Delta P = 1.8 \times 10^{10} \text{ N/m}^2$$

—————

8. A 40cm tall glass is filled with water to a depth of 30cm

A. What is the gauge pressure at the bottom of glass?

B. What is the absolute pressure at the bottom of glass?

Solution

Given $h = 30 \text{ cm} = 0.3 \text{ m}$ $P_{\text{water}} = 1 \times 10^3 \text{ kp/m}^2$
 $\bar{g} = 9.81 \text{ m/s}^2$

a) $P_{\text{gauge}} = \rho g h = (1000) (9.81) (0.3)$
 $= \underline{\underline{2.9 \times 10^3 \text{ Pa}}}$

b) $P_{\text{absolute}} = P_{\text{gauge}} + P_{\text{atm}}$
 $= 2.9 \times 10^3 \text{ Pa} + 1.01 \times 10^5 \text{ Pa}$

$$P_{\text{absolute}} = \underline{\underline{1.04 \times 10^5 \text{ Pa}}}$$

Example

Suppose that the tension in the cable is 940 N as the actor reaches the lowest point. What diameter should a 50-m long steel wire have if we do not want it to stretch more than 0.5 cm under these conditions?

Solution

$$F = 940 \text{ N} \quad \text{from definition of Young modulus}$$

$$l_0 = 50 \text{ m}$$

$$\Delta l = 0.5 \text{ cm} = 0.005 \text{ m} \quad Y = \frac{F_l}{A} \rightarrow A = \frac{F_l}{Y \Delta l}$$

$$d = ?$$

Since we are asked diameter we can get it from Area

$$\text{Also } Y = 20 \times 10^{10} \text{ N/m}^2 \text{ -- for steel wire}$$

$$\text{So } A = \frac{(940 \text{ N}) (50 \text{ m})}{(20 \times 10^{10} \text{ N/m}^2) (0.005 \text{ m})}$$

$$A = 9.4 \times 10^{-6} \text{ m}^2$$

$$\text{Because of radius of wire} \rightarrow A = \pi r^2$$

$$r = \sqrt{\frac{A}{\pi}} = \sqrt{\frac{9.4 \times 10^{-6} \text{ m}^2}{\pi}} = 1.7 \times 10^{-3} \text{ m} = 1.7 \text{ mm}$$

$$\text{So, } d = 2r = 2(1.7 \text{ mm}) = 3.4 \text{ mm}$$

Activity

A solid brass sphere is initially surrounded by air, and the air pressure exerted on it is $1.0 \times 10^5 \text{ N/m}^2$. The sphere is lowered into the ocean to a depth where the pressure is $2.0 \times 10^7 \text{ N/m}^2$. The volume of sphere in air is 0.50 m^3 . By how much does this volume change once the sphere is submerged?

Solution From definition of bulk modulus

$$B = -\frac{\Delta P}{\frac{\Delta V}{V_i}} \rightarrow \Delta V = -\frac{V_i \Delta P}{B}$$

Given

$$P_i = 1.0 \times 10^5 \text{ N/m}^2$$

$$P_f = 2.0 \times 10^7 \text{ N/m}^2$$

$$V_i = 0.5 \text{ m}^3$$

$$\Delta V = ?$$

$$B = 6.1 \times 10^{10} \text{ N/m}^2 \text{ for } \underline{\text{Brass}}$$

$$\text{So, } \Delta P = P_f - P_i \approx P_f = 2.0 \times 10^7 \text{ N/m}^2$$

B/c final pressure is much greater than initial pressure

$$\Delta V = -\frac{(0.5 \text{ m}^3)(2.0 \times 10^7 \text{ N/m}^2)}{6.1 \times 10^{10} \text{ N/m}^2}$$

$$\Delta V = -1.6 \times 10^{-4} \text{ m}^3 \rightarrow \text{-ve sign indicates decrease in volume}$$

Elasticity Moduli

The stress will be proportional to the strain if the stress is sufficiently small. In this regard, the proportionality constant known as elastic modulus depends on the material being deformed and on the nature of deformation.

$$\boxed{\text{Stress} = \text{elastic modulus} \times \text{strain}}$$

- There are 3 types of elastic modulus

1. Young's Modulus: is the ratio of tensile stress to tensile strain.

It measures the resistance of a solid to a change in its length and typically used to characterize a rod or wire stressed under either tension or compression.

$$\boxed{Y = \frac{\text{tensile stress}}{\text{tensile strain}} = \frac{F/A}{\Delta L/L_0}}$$

Y - has unit of force per Unit area

$$\boxed{Y \Rightarrow F/A = N/m^2}$$

2. Shear Modulus: it is the measure of the resistance to motion of the planes within a solid parallel to each other.

A material having large shear modulus is difficult to bend.

$$\boxed{S = \frac{\text{Shear Stress}}{\text{Shear Strain}} = \frac{\Delta F/A}{X/h}}$$

Its SI units pascal

3. Bulk Modulus: it measures the resistance of solids or liquids to changes in their volume

A material having a large bulk modulus doesn't compress easily.

$$\boxed{B = \frac{\text{Volume stress}}{\text{Volume strain}} = \frac{-\Delta F/A}{\Delta V/V_0} = \frac{-\Delta P}{\Delta V/V_0}}$$

* a negative sign is included in this defining equation, so that B is always positive.

* An increase in pressure (+ve ΔP) causes a decrease in volume negative (ΔV) and vice versa.

* Strain Energy is the energy stored in a stretched wire.

If x is due to applied force F ,

$$\boxed{\text{Strain Energy} = \frac{1}{2} k x^2}$$

Density and pressure in static fluids

Density (ρ) is the quantity of mass (m) per Unit Volume (V) of a body with SI unit kg/m^3 and given by $P = \frac{m}{V}$

Specific gravity (SG) is the ratio of density of a substance to the density of another substance which is taken as standard.

→ The density of pure water at 4°C = $1.0 \times 10^3 \text{ kg/m}^3$ - taken as standard

- The SG is dimensionless quantity and the same in any system of measurement

Example: The density of aluminum is $2.7 \times 10^3 \text{ kg/m}^3$

$$\therefore \text{the SG of Al is } SG = \frac{2.7 \times 10^3 \text{ kg/m}^3}{1.0 \times 10^3 \text{ kg/m}^3} = \underline{\underline{2.7}}$$

Example: A solid sphere made of wood has a radius of 0.1m . The mass of sphere is 1.0 kg . Determine a) density b) SG

Solution: The volume of sphere wood is $V = \frac{4}{3}\pi r^3$

Given: $r = 0.1\text{m}$ $m = 1\text{ kg}$

$$= \frac{4}{3}\pi(0.1)^3 = \underline{\underline{4.18 \times 10^{-3} \text{ m}^3}}$$

So a) density $\rightarrow P = \frac{m}{V} = \frac{1\text{ kg}}{4.18 \times 10^{-3} \text{ m}^3} = \underline{\underline{239 \text{ kg/m}^3}}$

b) $SG \rightarrow SG = \frac{\text{density of wood}}{\text{density of water}} = \frac{239 \text{ kg/m}^3}{1 \times 10^3 \text{ kg/m}^3}$

$$SG = \underline{\underline{0.239}}$$

Pressure: is the ratio of force acting perpendicular to surface Area (A) on which the force acts.

- SI Unit N/m^2 , called pascal (Pa)

- Another pressure unit is atmosphere (atm) equal to 101.3 kPa which is average pressure exerted by the Earth's atm at sea level

$$P = \frac{F}{A}$$

→ pressure produced by the column of fluid of height h and density ρ is given by $P_{\text{fluid}} = \rho gh$

Note that

- All points at same level in a fluid have same pressure
- Fluid pressure increase with increase in the depth of fluid
- Fluid pressure does not depend on the shape of container

Atmospheric pressure is the pressure due to weight of atmosphere exerted on the surface of Earth.

→ Atmospheric pressure decrease with increase in altitude (due to decrease in density of air)

Gauge pressure is the difference in pressure b/w a system and surrounding atmosphere

$$P_{\text{gauge}} = P_{\text{system}} - P_{\text{atmosphere}}$$

Gauge pressure is relative to atmospheric pressure

positive for pressure above atmospheric pressure
negative for below it

Absolute pressure is the total pressure

Cannot be negative Pa

$$P_{\text{absolute}} = P_{\text{gauge}} + P_{\text{atmosphere}}$$

→ Smallest absolute pressure is zero. Thus, smallest possible gauge pressure

$$\text{is } P_{\text{gauge}} = -P_{\text{atmosphere}}$$

Example

A submerged wreck is located 18.3m beneath the surface of the ocean off the coast of South Florida. Determine

a) P_{gauge} b) P_{abs}

(Note → density of sea water is 1025 kg/m^3)

Solution

$$\text{a) } P_{\text{gauge}} = \rho gh = (1025 \text{ kg/m}^3) (9.8 \text{ m/s}^2) (18.3 \text{ m}) = 1.83 \times 10^5 \frac{\text{N}}{\text{m}^2}$$

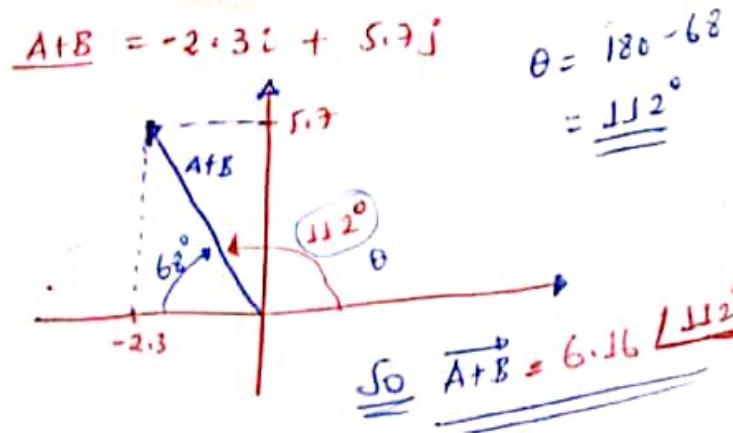
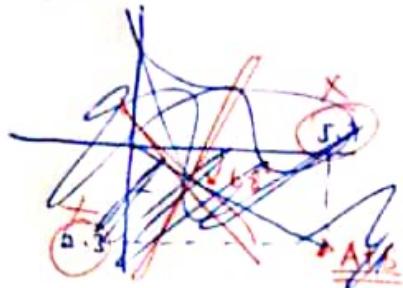
$$P_{\text{gauge}} = 1.83 \times 10^5 \frac{\text{N}}{\text{m}^2} = 183 \text{ kPa}$$

$$\text{b) } P_{\text{abs}} = P_{\text{gauge}} + P_{\text{atm}}$$

$$= (1.83 \times 10^5 + 1.013 \times 10^5) \frac{\text{N}}{\text{m}^2}$$

$$= 2.84 \times 10^5 \frac{\text{N}}{\text{m}^2} = 284 \text{ kPa}$$

Graph of A+B



- ③ If $A = 6i - 8j$, $B = -8i + 3j$, $C = 26i + 19j$
find a & b such that $aA + bB + C = 0$.

Soln

$$aA = 6ai - 8aj$$

$$bB = -8bi + 3bj$$

$$C = 26i + 19j$$

$$\text{Given } aA + bB + C = 0i + 0j$$

$$(6a - 8b + 26)i + (-8a + 3b + 19)j = 0i + 0j$$

So

$$6a - 8b + 26 = 0 \quad \dots \textcircled{1}$$

$$-8a + 3b + 19 = 0 \quad \dots \textcircled{2}$$

$$6a - 8b = -26 \quad \dots \text{divide by 2}$$

$$-8a + 3b = -19$$

$$(3a - 4b = -13) \times 3$$

$$(-8a + 3b = -19) \times 4$$

$$9a - 12b = -39$$

$$-32a + 12b = -76$$

$$\frac{-23a}{-23} = \frac{-115}{-23}$$

$$a = \frac{-115}{-23} = \frac{115}{23}$$

$$a = \underline{\underline{5}}$$

Put a into equation

$$-8a + 3b = -19$$

$$-8(\underline{\underline{5}}) + 3b = -19$$

$$-40 + 3b = -19$$

$$3b = -19 + 40$$

$$3b = 21$$

$$b = \frac{21}{3}$$

$$b = \underline{\underline{7}}$$

So, The Value of

$$\underline{\underline{a = 5 \text{ and } b = 7}}$$

(2)

Example

A sample of an unknown material weighs 300N in air & 200N when submerged in alcohol (solute) with a density of $0.7 \times 10^3 \text{ kg/m}^3$. What is density of material?

Solution

Given

$$W_{\text{air}} = 300\text{N}$$

$$W_{\text{alcohol}} = 200\text{N}$$

$$\rho_{\text{alcohol}} = 0.7 \times 10^3 \text{ kg/m}^3$$

$$\rho_{\text{material}} = ? (\rho_0)$$

$$F_{\text{buoyant}} = W_{\text{air}} - W_{\text{alcohol}}$$

$$= 300 - 200$$

$$= 100\text{N}$$

$$\frac{W_{\text{air}}}{F_{\text{buoyant}}} = \frac{\rho_0}{\rho_{\text{alcohol}}} \Rightarrow \rho_0 = \frac{W_{\text{air}} \times \rho_{\text{alcohol}}}{F_{\text{buoyant}}}$$

$$= \frac{(0.7 \times 10^3) \times (300)}{100}$$

$$\rho_0 = \underline{\underline{0.1 \times 10^3 \text{ kg/m}^3}}$$

Moving Fluids & Bernoulli equation

- If the flow is steady, then the velocity of the fluid particles at any point is a constant with time. The various layers of the fluid slide smoothly past each other. This is called Streamline or Laminar flow.
- Turbulent flow is the irregular movement of particles in a fluid and results in loss of energy due to internal friction b/w neighboring layers of the fluid, called Viscosity.
- * Factors affecting laminar flow are density, compressibility, temperature and viscosity.

Assumptions

- * The fluid is non-viscous → There is no internal friction b/w adjacent layers
- * The flow is steady → The velocity of fluid at each point remains constant
- * The fluid is incompressible → Density of fluid is constant
- * The flow is irrotational → The fluid has no angular momentum about any point.

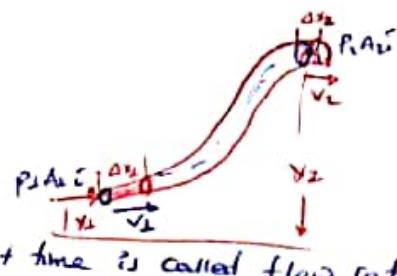
Equation of Continuity

Equation of continuity expresses conservation of mass for an incompressible fluid flowing in a tube. It says « the amount (either mass or volume) of fluid flowing through a cross section of tube in a given time interval must be the same for all cross-sections. Or the product of the area and the fluid speed at all points along a tube is constant for an incompressible fluid.

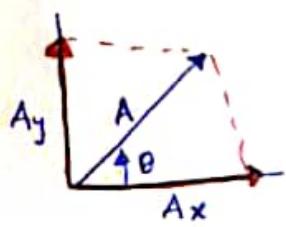
$$A_1 V_1 = A_2 V_2$$

$$\boxed{\text{flow rate} = \frac{\text{Volume}}{\text{time}} = A_1 V_1 = \text{constant.}}$$

→ When cross sectional area is decreased then the flow rate increases
The product $A_1 V_1$, which has the dimensions of volume per unit time is called flow rate



1.3.3 Components of Vector



$$\cos \theta = \frac{Ax}{A} \rightarrow Ax = A \cos \theta \quad \text{x component of } A$$

$$\sin \theta = \frac{Ay}{A} \rightarrow Ay = A \sin \theta \quad \text{y component of } A$$

Resultant $\rightarrow A = Ax + Ay$

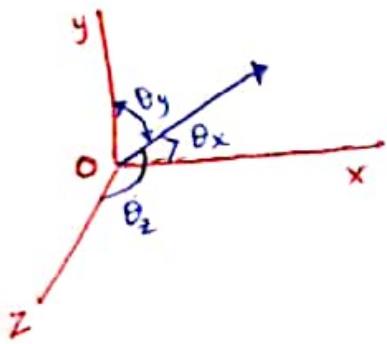
Magnitude of resultant $\rightarrow A = \sqrt{Ax^2 + Ay^2}$

→ for 3 dimension

x, y, z

$$\text{Resultant } R = Rx + Ry + Rz$$

$$\text{Magnitude } R = \sqrt{Rx^2 + Ry^2 + Rz^2}$$



$$\cos \theta_x = \frac{Rx}{R} \Rightarrow \theta_x = \cos^{-1}\left(\frac{Rx}{R}\right) \quad \begin{matrix} \nearrow \text{direction of} \\ \nearrow \text{coincide} \end{matrix} \quad \begin{matrix} \nearrow \text{direction} \\ \nearrow \text{angles} \end{matrix}$$

$$\cos \theta_y = \frac{Ry}{R} \Rightarrow \theta_y = \cos^{-1}\left(\frac{Ry}{R}\right)$$

$$\cos \theta_z = \frac{Rz}{R} \Rightarrow \theta_z = \cos^{-1}\left(\frac{Rz}{R}\right)$$

1.4 Unit Vector

- A unit vector is a vector that has magnitude of one and
 - it is dimensionless
 - its sole purpose is to point a given vector in specified direction.
 - it is usually denoted by with a "hat"

$$A = A\hat{u}$$

Any Vector can be expressed in terms of Unit Vectors

2-dimension

$$A = Ax\hat{i} + Ay\hat{j}$$

$$\overset{3D}{=} A = Ax\hat{i} + Ay\hat{j} + Az\hat{k}$$

Addition Let $\vec{A} = Ax\hat{i} + Ay\hat{j} + Az\hat{k}$

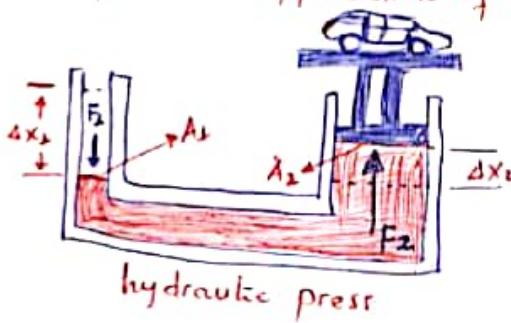
$$\vec{B} = Bx\hat{i} + By\hat{j} + Bz\hat{k}$$

$$\vec{A} + \vec{B} = (Ax + Bx)\hat{i} + (Ay + By)\hat{j} + (Az + Bz)\hat{k}$$

Buoyant Force and Archimede's Principle

Pascal's principle - states that pressure applied to a confined fluid in a container is transmitted equally to all regions of the fluid and to the walls of the container.

- An important application of pascal's principle is the hydraulic press



$$P_2 = \frac{F_2}{A_2}$$

$$P_1 = \frac{F_1}{A_1}$$

According to pascal's principle

$$P_1 = P_2$$

$$\hookrightarrow \frac{F_1}{A_1} = \frac{F_2}{A_2}$$

Example

A small piston of a hydraulic lift has an area of 0.20 m^2 . A car weighing $5.2 \times 10^4 \text{ N}$ sits on a rack mounted on the large piston. The large piston has an area of 0.90 m^2 . How large force must be applied to the small piston to support the car.

Given

$$A_1 = 0.2 \text{ m}^2$$

$$A_2 = 0.9 \text{ m}^2$$

$$F_2 = 5.2 \times 10^4 \text{ N}$$

$$F_1 = ?$$

According to pascal's principle

$$\frac{F_1}{A_1} = \frac{F_2}{A_2}$$

$$\text{So, } F_1 = F_2 \left(\frac{A_1}{A_2} \right) = 5.2 \times 10^4 \left(\frac{0.2 \text{ m}^2}{0.9 \text{ m}^2} \right)$$

Archimede's principle

$$F_1 = \underline{\underline{2.7 \times 10^4 \text{ N}}}$$

Archimede's principle states anybody completely or partially submerged in a fluid is buoyed up by a force equal to the weight of the fluid displaced by the body

$$F_{\text{buoyant}} = W_{\text{fluid}} = \rho_{\text{fluid}} V_{\text{displaced fluid}} g$$

→ Any object which is partially or totally submerged in a liquid has buoyant force acting on it which pushes the object up.

→ Pressure of the fluid is dependent on the depth of the fluid

So. pressure at the top of an object is less than pressure at the bottom of the object.

Finding a Unit Vector

Consider any vector

$$\vec{r} = xi + yj + zk$$

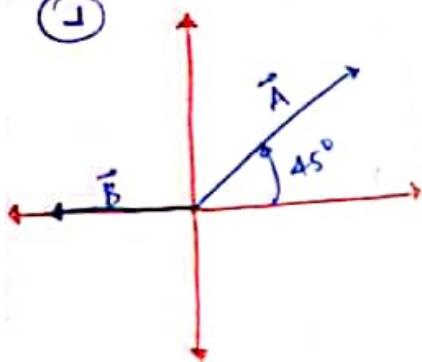
The Unit Vector \hat{r} in the same direction is simply vector \vec{r} divided by its magnitude r .

Unit vector in the same direction

$$\hat{r} = \frac{\vec{r}}{r} = \frac{xi + yj + zk}{\sqrt{x^2 + y^2 + z^2}} = \frac{x}{r}\hat{i} + \frac{y}{r}\hat{j} + \frac{z}{r}\hat{k}$$

Chapter Review question/solution/

(1)



find a) magnitude & direction $\vec{A} + \vec{B}$
b) magnitude and direction of $\vec{A} - \vec{B}$

Solution

$$\vec{A} = Ax\hat{i} + Ay\hat{j} \quad Ax = A \cos \theta \quad Ay = A \sin \theta$$

Given
 $A = 8 \text{ unit}, \theta_1 = 45^\circ$
 $B = 8 \text{ unit}, \theta_2 = 0^\circ$

$$\text{So } Ax = 8 \cos 45^\circ = 8 \times \frac{\sqrt{2}}{2} = 4\sqrt{2}$$
$$Ay = 8 \sin 45^\circ = 8 \times \frac{\sqrt{2}}{2} = 4\sqrt{2}$$

$$\vec{B} = Bx\hat{i} + By\hat{j}$$

$$Bx = B \cos \theta_2 = -8 \cos 0^\circ = -8 \times 1 = -8$$

$$By = B \sin \theta_2 = -8 \sin 0^\circ = -8 \times 0 = 0$$

So Resultant \vec{R}

$$\vec{A} = Ax\hat{i} + Ay\hat{j} = 4\sqrt{2}\hat{i} + 4\sqrt{2}\hat{j}$$

$$\vec{B} = Bx\hat{i} + By\hat{j} = -8\hat{i} + 0\hat{j} = -8\hat{i}$$

$$\begin{aligned} \vec{A} + \vec{B} &= (Ax + Bx)\hat{i} + (Ay + By)\hat{j} \\ &= (4\sqrt{2} - 8)\hat{i} + 4\sqrt{2}\hat{j} \\ &= (-2.3)\hat{i} + 5.7\hat{j} \end{aligned}$$

$$\boxed{\vec{A} + \vec{B} = -2.3\hat{i} + 5.7\hat{j}}$$

$$4\sqrt{2} = 5.656$$
$$\approx 5.7$$

Magnitude of $\vec{A} + \vec{B} = \sqrt{(-2.3)^2 + (5.7)^2} = \sqrt{37.98} = 6.16$

Direction of $\vec{A} + \vec{B} \Rightarrow \theta = \tan^{-1}\left(\frac{5.7}{-2.3}\right) = -68^\circ$

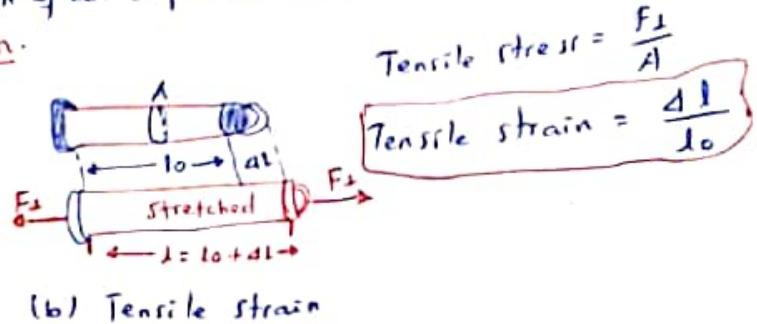
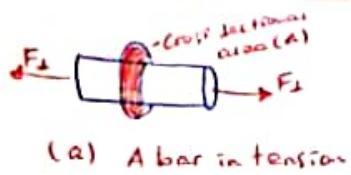
(6)

$$\text{Lpso } \theta = 180 - \alpha = 180 - 68^\circ = 112^\circ$$

1. Tensile strain

$$\text{Tensile stress} = \frac{\text{the ratio of the force magnitude}}{\text{cross-sectional area}} = \frac{F_1}{A}$$

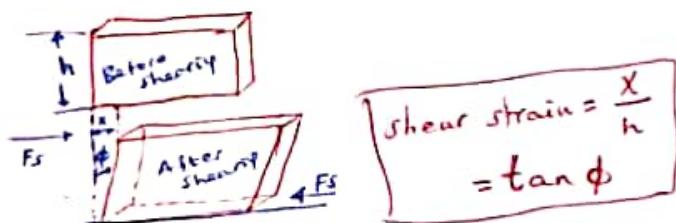
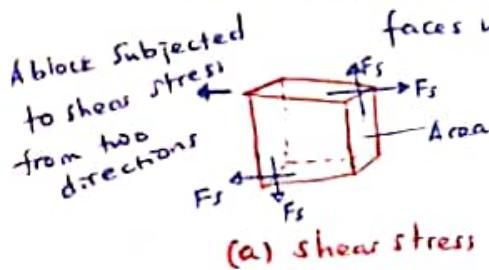
* The fractional change in length of an object under a tensile stress is called the tensile strain.



$$\text{Tensile strain} = \frac{\Delta l}{l_0}$$

2. Shear stress and strain

Shear stress - When an object is subjected to a force parallel to one of its faces while the opposite face is held fixed by another force.



$$\text{(b) shear strain} = \frac{x}{h}$$

$$= \tan \phi$$

→ Shear strain is defined as the ratio $\frac{x}{h}$, where x is the horizontal distance that the sheared face moves and h is the height of the object.

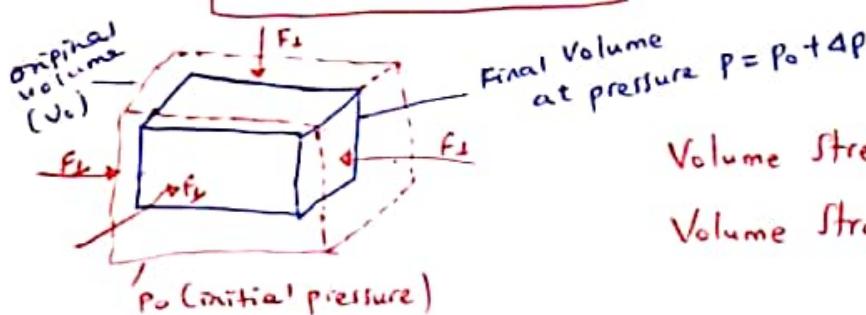
3. Volume stress and strain

Volume Stress is a stress which causes volume deformation on an object and defined as the ratio of change in the magnitude of applied force ΔF to the surface A

$$\text{Volume stress} = \frac{\Delta F}{A}$$

Volume Strain is the fraction change in Volume that is - the change in Volume, ΔV divided by original Volume, V_0

$$\text{Volume Strain} = \frac{\Delta V}{V_0}$$



$$\text{Volume stress} = \Delta P$$

$$\text{Volume strain} = \frac{\Delta V}{V_0}$$

A lens is a part of transparent thick glass which is bounded by two spherical surfaces. It is an optical device through which the rays of the light converge or diverge before transmitting.

Convex lenses: Converging lenses thickest at their center and converge a beam of parallel light to real focus.

Concave lenses: Diverging lenses thinnest at their center and diverge a beam of parallel light from virtual focus.

The distance from the focal point to the lens is called focal ~~length~~ length (f).

The equation that relates object and image distances for a lens is identical to the mirror equation

$$\frac{1}{s_o} + \frac{1}{s_i} = \frac{1}{f}$$

Magnification is defined as the ratio of image height (h_i) to object height (h_o) or ratio of image distance (s_i) to object distance (s_o).

$$m = \frac{h_i}{h_o} = \frac{s_i}{s_o}$$

Generally the image formed by a convex lens has the following features.

→ If an object is brought close to the lens, the size of image keeps on increasing.

→ As it goes more close to the lens, the image all the more enlarged.

The images formed will be diminished inverted images, small sizes inverted images, enlarged inverted images, and enlarged erect images. In concave lens there is a possibility of getting real as well as an inverted image.

4) Find a Unit Vector in the direction of resultant Vectors

$$A = 2i - 3j + k$$

$$B = i + j + 2k$$

$$C = 3i - 2j + 4k$$

Solution

$$\vec{A}_m = \frac{\vec{A}}{|A|}$$

$$\vec{A}_m = \frac{2i - 3j + k}{\sqrt{14}} = \underline{\underline{\frac{2}{\sqrt{14}}i - \frac{3}{\sqrt{14}}j + \frac{1}{\sqrt{14}}k}}$$

$$\vec{B}_m = \frac{i + j + 2k}{\sqrt{6}} \rightarrow |B| = \sqrt{1^2 + 1^2 + 2^2}$$

$$\text{So } \vec{B}_m = \frac{\vec{B}}{|B|} = \underline{\underline{\frac{i + j + 2k}{\sqrt{6}}}}$$

$$\vec{B}_m = \underline{\underline{\frac{1}{\sqrt{6}}i + \frac{1}{\sqrt{6}}j + \frac{2}{\sqrt{6}}k}}$$

$$\vec{C}_m = 3i - 2j + 4k$$

$$\vec{C}_m = \frac{\vec{C}}{|C|} \quad |C| = \sqrt{3^2 + (-2)^2 + 4^2}$$

Finish it

(9)

4) Find a Unit Vector in the direction of resultant Vectors

$$A = 2\mathbf{i} - 3\mathbf{j} + \mathbf{k}$$

$$B = \mathbf{i} + \mathbf{j} + 2\mathbf{k}$$

$$C = 3\mathbf{i} - 2\mathbf{j} + 4\mathbf{k}$$

Solution

$$\vec{A}_m = \frac{\vec{A}}{|A|}$$

$$|A| = \sqrt{2^2 + (-3)^2 + (1)^2} \\ = \sqrt{4 + 9 + 1} = \underline{\underline{\sqrt{14}}}$$

$$\vec{A}_m = \frac{2\mathbf{i} - 3\mathbf{j} + \mathbf{k}}{\sqrt{14}} = \underline{\underline{\frac{2}{\sqrt{14}}\mathbf{i} - \frac{3}{\sqrt{14}}\mathbf{j} + \frac{1}{\sqrt{14}}\mathbf{k}}}$$

$$\vec{B}_m = \frac{\vec{B}}{|B|} \rightarrow |B| = \sqrt{1^2 + 1^2 + 2^2}$$

$$\text{So } \vec{B}_m = \frac{\vec{B}}{|B|} = \frac{\mathbf{i} + \mathbf{j} + 2\mathbf{k}}{\sqrt{6}}$$

$$\vec{B}_m = \underline{\underline{\frac{1}{\sqrt{6}}\mathbf{i} + \frac{1}{\sqrt{6}}\mathbf{j} + \frac{2}{\sqrt{6}}\mathbf{k}}}$$

$$\vec{C}_m = 3\mathbf{i} - 2\mathbf{j} + 4\mathbf{k}$$

$$\vec{C}_m = \frac{\vec{C}}{|C|} \quad |C| = \sqrt{3^2 + (-2)^2 + 4^2} \\ =$$

Finish it

(9)

CHAPTER - 3

FLUID MECHANICS

Fluid

mechanics is the branch of physics concerned with the mechanics of fluids in motion (fluid dynamics) or at rest (fluid statics) & forces on them.

→ a fluid is a substance that continually deforms (flows) under an applied shear stress, or external force.

Fluids are a phase of matter include liquids and gases.

Properties of Bulk Matter

a solid may be thought of as having a definite shape and volume, it's possible to change its shape and volume by applying external forces.

→ A sufficiently large force will permanently deform or break an object, but otherwise, when the external forces are removed, the object tends to return to its original shape and size is called elastic behaviour.

Elastic materials are materials that regain their original shape and size when the deforming force is removed.

Elastic deformation is a reversible deformation by a force applied within the elastic limit.

→ Beyond elastic limit, a force applied on an object causes permanent and irreversible deformation called plastic deformation.

Plastic materials do not regain their original shape and size when the deforming force is removed.

The elastic properties of solid materials are described in terms of stress & strain.
Stress: is the force per unit area that is causing some deformation. It has SI unit N/m^2 called the pascal (pa), the same as unit of pressure.

$$\boxed{\text{Stress} = \frac{F}{A}}$$

Strain: measures the amount of deformation by applied stress and defined as the change in configuration of a body divided by its initial configuration.

strain is Unit less quantity.

$$\text{Strain} = \frac{\text{Change in Configuration}}{\text{Initial Configuration}}$$

There are 3 kinds of strains

- 1) Tensile strain
- 2) shear stress and strain
- 3) Volume stress and strain

$$\textcircled{1} \text{ Measurement} = X_{\text{best}} \pm 6x$$

Where X_{best} = best estimate of measurement

$6x$ = Uncertainty (error) in measurement.

1.2. Significant digits

→ If zero has a non-zero digit anywhere to its left, then zero is significant

Otherwise it is not

Eg → 7.00 has 3 significant figures

→ 0.0007 has only 1 significant figure

→ 1.0007 has 5 sf

→ 300 - Not well defined, Rather $3 \times 10^2 \rightarrow$ has 1 sf or $3.00 \times 10^2 \rightarrow$ has 3 sf

$\textcircled{2}$ When writing numbers, zeros used only to help in locating the decimal point are not significant.

Rules for Significant figures

Rule 1 → When approximate numbers are multiplied/divided, the no. of significant digits in the final answer is the same as the no. of significant digits in the least accurate of factors

$$\text{Ex: } X = \frac{45}{(3.21 \text{ m}) \times (2.00 \text{ m})} = \underline{\underline{6.97015 \text{ N/m}}}$$

→ Least significant factor is 45 has only two digits so the answer should be

$$X = 7.0 \text{ N/m}$$

Rule 2 → When approximate no. are added or subtracted, the no. of significant digits should equal the smallest no. of decimal places of any term in the sum or difference

$$\text{Ex: } \underline{\underline{9.65 \text{ cm}}} + \underline{\underline{8.4 \text{ cm}}} - \underline{\underline{0.89 \text{ cm}}} = 15.16 \text{ cm}$$

⇒ It should be → 15.2 cm

In general to determine significant digits in a given number

1. All non-zero numbers are significant

2. Zeros within a no. are always significant

3. Zeros that do nothing but set the decimal point are not significant Eg 0.000098 & 0.98 has 2 significant.

4. Zeros that aren't needed to hold the decimal points are significant Eg. 4.00 has 3 significant.

5. Zeros that follow a number may be significant.

CHAPTER- REVIEW QUESTION

1. How would the period of a simple pendulum be affected if it were located on the moon instead of the earth?

Solution

The time period of Simple pendulum is $T = 2\pi\sqrt{\frac{l}{g}}$. The time period is inversely proportional to acceleration due to gravity.

Time period could increase by \sqrt{G} when compared to earth.

Hence, pendulum should swing slower and the frequency will also be on the lower side.

2. What effect would the temperature have on the time kept by a pendulum clock if the pendulum rod increases in length with an increase in temperature.

Solution

→ A major source of error in pendulum clocks is in thermal expansion. The pendulum rod changes in length slightly with change in temperature, causing changes in the rate of the clock.

→ An increase in temperature causes the rod to expand, making the pendulum longer, so its period increases and the clock loses time.

3. What kind of graph would result if the period T were graphed as a function of the square root of the length l .

Solution

We are talking of a simple pendulum so period $T = 2\pi\sqrt{\frac{l}{g}}$

• $\left(\frac{2\pi}{\sqrt{g}}\right)$ is constant $\rightarrow \left(\frac{2\pi}{\sqrt{g}}\right)\sqrt{l}$
for a given location.

So

We can write $T = k\sqrt{l}$ where $k = \frac{2\pi}{\sqrt{g}}$ is constant.

→ Thus, The graph of the period T , as a function of the square root of the length l , would be a straight line with slope

$$k = \frac{2\pi}{\sqrt{g}}$$

1.3 Vectors: Composition and Resolution

Scalar: is a quantity that is completely specified by a no. and Unit

- it has magnitude but not direction

Ex mass, time, Volume, Speed etc

Vector: is a quantity that has both specified by a magnitude & direction.

Ex displacement, Velocity, acceleration, momentum etc.

Vector Representation

A) Algebraic Method: Vectors are represented algebraically by a letter (or symbol) with an arrow at its head

Ex Velocity $\rightarrow \vec{V}$, momentum $\rightarrow \vec{P}$

Magnitude of a Vector is a positive scalar b
Written as either $|A|$ or A

Geometric Method

Ex. $\vec{A} + \vec{B} \Rightarrow$ it means beginning of vector \vec{A} to end of another

* A Vector changes if its magnitude or direction or if both magnitude and direction change.

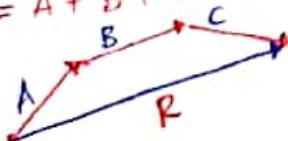
Vector Addition

Graphical Method

parallelogram Method

A) Graphical method: can be added by joining their head to tail and in any order their resultant vector is the vector drawn from the tail of the first vector to head of the last vector

Ex $R = A + B + C$

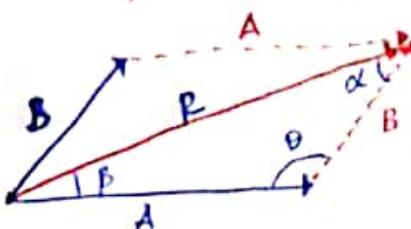


* A single vector that is obtained by adding two or more vectors is called Resultant Vector.

B) parallelogram method

1) Cosine law: $R = \sqrt{A^2 + B^2 - 2AB \cos \theta}$

2) Sine law: $\frac{\sin \theta}{R} = \frac{\sin \alpha}{A} = \frac{\sin \beta}{B}$



where

θ = angle b/w Vector A and B

R = Resultant

1.3 Vectors: Composition and Resolution

Scalar: is a quantity that is completely specified by a no. and Unit

- it has magnitude but not direction

Ex mass, time, Volume, Speed etc

Vector: is a quantity that has both specified by a magnitude & direction.

Ex displacement, Velocity, acceleration, momentum etc.

Vector Representation

A) Algebraic Method: Vectors are represented algebraically by a letter (or symbol) with an arrow at its head

Ex Velocity $\rightarrow \vec{V}$, momentum $\rightarrow \vec{P}$

Magnitude of a Vector is a positive scalar b
Written as either $|A|$ or A

Geometric Method

Ex. $\vec{A} + \vec{B} \Rightarrow$ it means beginning of vector \vec{A} to end of another vector \vec{B}

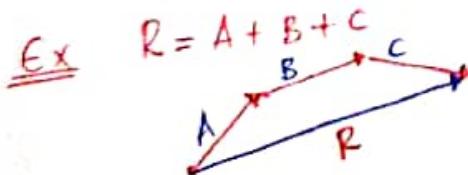
* A Vector changes if its magnitude or direction or if both magnitude and direction change.

Vector Addition

Graphical Method

parallelogram Method

A) Graphical method: can be added by joining their head to tail and in any order their resultant vector is the vector drawn from the tail of the first vector to head of the last vector

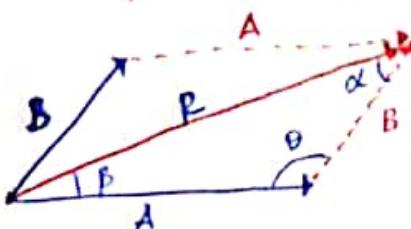


* A single vector that is obtained by adding two or more vectors is called Resultant Vector.

B) Parallelogram method

1) Cosine law: $R = \sqrt{A^2 + B^2 - 2AB \cos \theta}$

2) Sine law: $\frac{\sin \theta}{R} = \frac{\sin \alpha}{A} = \frac{\sin \beta}{B}$



where

θ = angle b/w Vector A and B

R = Resultant

3) Conversion of Units

To convert a quantity from one unit to another multiply by conversions factors

Ex

<u>Quantity</u>	<u>From</u>	<u>To</u>	<u>Operation</u>
Length	inch (in)	m	(inch) * 0.0254
	foot (ft)	m	(foot) * 0.3048
	mile (mi)	m	(mile) * 1609.34
<u>Mass</u>	pound (lb)	kg	(pound) * 0.4536
	metric ton (t)	kg	(ton) * 1000
	ounce	kg	(ounce) * 0.02835
<u>Volume</u>	litre (l)	m^3	(litre) * 0.001
	gallon (gal)	m^3	(gallon) * 0.00379
Temperature	Fahrenheit (F)	K	$(F - 32) \times \frac{5}{9} + 273.15$
	Celsius (C)	K	C + 273.15

Example: 1) 0.02 in \rightarrow m

Solution $0.02 \text{ in} = 0.02 \times 0.0254 \text{ m} = 0.000508 \text{ m} = \underline{\underline{5.08 \times 10^{-4} \text{ m}}} \text{ or } \underline{\underline{0.503 \text{ mm}}}$

2) Honda fit weights about 2,500 lb to kg

$$\begin{aligned} \text{Soln} \quad & 2,500 \times 0.4536 \\ & = \underline{\underline{1134.0 \text{ kg}}} \end{aligned}$$

1.2 Uncertainty in Measurement and Significant Digits

Uncertainty - gives the range of possible values of measure and WIC covers true value of measure

All measurements always have some uncertainty.

Errors fall in two categories

1) Systematic Error: Errors resulting from measuring devices being out of calibration

2) Random Error: Resulting in the fluctuation of measurements of the same quantity about the average.

④ Uncertainty in a scale measuring device is equal to the smallest increment divided by 2

$$6x = \frac{\text{Smallest increment}}{2}$$

Example: Meter stick (scale device) $\rightarrow 6x = \frac{1 \text{ mm}}{2} = 0.5 \text{ mm} = \underline{\underline{0.05 \text{ cm}}}$

⑤ Uncertainty in a digital measuring device is equal to Smallest increment $6x = \text{Smallest increment}$

Example: A reading from digital balance (digital device) is 5.2513 Kg therefore $6x = 0.0001$

- * **Wavelength (λ):-** distance b/w any two consecutive points which are in phase.
- * **Period (T):-** is the time taken by a wave to move one wavelength
- * **frequency(f):-** number of oscillations performed per unit time
- * **Speed (v):** is constant in a medium provided the medium is homogeneous

$$V = \lambda f$$

Types Of Waves

- * Based on the need of material medium for its propagation

- 1) **Mechanical Waves:** are waves produced by oscillation of particles of a mechanical medium and need medium for propagation

Ex. Water waves, Sound waves, wave in strings etc

All mechanical wave requires

- ✓ Some source of disturbance
- ✓ a medium that can be disturbed and
- ✓ physical medium through which elements of medium can influence each other

- 2) **Electromagnetic (EM) Waves:-** are produced by accelerated charged particles and can propagate through both material medium & Vacuum.

Ex light, radio & TV waves, microwaves, X-rays etc

All EM wave in Vacuum propagate with Speed $C = 3 \times 10^8 \text{ m/s}$

- * Based on the way they are propagating

\rightarrow Transverse
 \rightarrow Longitudinal

- 1) **Transverse Wave:-** Where particles of the disturbed medium oscillate perpendicular to the direction of wave motion.

Ex. Water waves, Waves on strings & most all EM waves.

Sinusoidal graphs can represent this motion.

- 2) **Longitudinal Wave:-** is a wave where particles of the disturbed medium oscillate parallel to the direction of wave motion.

Ex Sound wave

2) Refraction of wave

It is the change in direction of wave passing from one medium to another caused by its change in speed.

3) Diffraction of wave

→ It is the spreading of waves around obstacles.

→ Diffraction takes place with sound, with electromagnetic radiation, such as light, X-rays & gamma rays

4) Interference of wave

The net effect of combination of two or more wave trains moving on intersecting or coincident paths.

Interference also occurs between two wave trains moving in the same direction but having different wavelengths or frequencies.

A pulsating frequency, called a beat, results when the wavelength are slightly different.

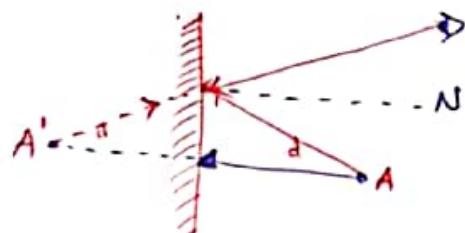
Image formation by thin lenses and mirrors

→ Images Formed by plane mirrors

If the reflecting surface of the mirror is flat, we call this type of

mirror as plane mirror.

→ Light always has regular reflection on plane mirrors.



* We have to see the rays coming from the object to see it. If the light first hits the mirror and then reflects with the same angle, the extensions of the reflected rays are focused at one point behind the mirror. We see the coming rays as if they are coming from behind of the mirror.

→ At point A' image of the point is formed and we call this image Virtual image which means not real.

The distance of image of the mirror = distance of object to the mirror

→ Images formed by lenses :- Lenses are commonly used to form images by refraction in optical instruments such as cameras, telescopes and microscopes.

A lens is an optical system with two refracting surfaces.

The two types of lenses are

1) Convex lenses

2) Concave lenses.

Special Online Tutorial General Physics

1.1 Physical Quantities and Measurement

Physical Quantity :- is a quantifiable or assignable property ascribed to a particular phenomenon or body.

Measurement :- is act of comparing a physical quantity with certain standard.

1. physical quantities

A) Basic physical quantities :- We cannot be expressed in terms of any other physical quantity
Example : length, mass and time

B) Derived physical quantities :- can be expressed in terms of fundamental quantities
Example : Area, Volume, Density

④ Measurements of physical quantities are expressed in terms of Units
Ex Length in meters or kilometers

2. SI Units: Basic and Derived Units

SI → International System of Units

Dimensions

7 → Basic quantities and their SI Unit

1. Length → L → meter (m) → L
2. Mass → m → kilogram (kg) → M
3. Time → t → Second (s) → T
4. Temperature → T → Kelvin (K) → Θ
5. Electric Current → I → ampere (A) → I
6. Amount of Substance → N → mole (N) → L
7. Luminous Intensity → F → candela (Cd) → J

Derived quantities, their SI Units & dimensions

Property	Symbol	Unit	Dimension
Force	F	newton (N)	$\text{kg} \cdot \text{m/s}^2$
Speed	V	m/s	m/s
pressure	P	Pascal (pa)	$\text{kg/m}^2 \text{ (force per unit area)}$
Energy	E	Joule (J)	$\text{kg m}^2/\text{s}^2$
Power	W	watt (W)	$\text{kg m}^2/\text{s}^3$

5.4 Resonance

→ Resonance is the increase in amplitude of oscillation of an electric or mechanical system exposed to a periodic force whose frequency is equal or very close to the natural undamped frequency of the system.

* The frequency at which the system starts oscillating or vibrating at higher amplitude is called the resonant frequency of the system.

Example: Swinging of a person sitting on a swing.

Doppler Effect

The Doppler effect is observed whenever the source of waves is moving with respect to an observer.

It can be described as the effect produced by a moving source of waves in which there is an apparent upward shift in frequency for observers towards whom the source is approaching & an apparent downward shift in frequency for observers from whom the source is receding.

The Doppler effect can be observed for any type of wave; Water wave, sound wave, light wave, etc.

Let f_o = frequency heard by observer & f_s = frequency emitted by source

Let v_o , v and v_s respectively Velocity of observer, sound wave & source

The observed frequency due to Doppler effect is

$$f_o = f_s \left(\frac{v \pm v_o}{v \mp v_s} \right)$$

"Upper" signs (i.e. $+v_o$ & $-v_s$) refer to motion of one towards other.

"Lower" signs (i.e. $-v_o$ & $+v_s$) refer to motion of one away from other.

Characteristics of Waves

The characteristics of waves are important in determining the size of waves, the speed at which they travel, how they break on shore and much more.

Example

① Reflection of Waves:

Whenever a travelling wave reaches a boundary, part or all of the wave bounces back. This phenomenon (rebouncing of wave from a surface) is called reflection.

5.4 Resonance

→ Resonance is the increase in amplitude of oscillation of an electric or mechanical system exposed to a periodic force whose frequency is equal or very close to the natural undamped frequency of the system.

* The frequency at which the system starts oscillating or vibrating at higher amplitude is called the resonant frequency of the body.

Example:- Swinging of a person sitting on a swing.

Doppler Effect

The Doppler effect is observed whenever the source of waves is moving with respect to an observer.

It can be described as the effect produced by a moving source of waves in which there is an apparent upward shift in frequency for observers towards whom the source is approaching & an apparent downward shift in frequency for observers from whom the source is receding.

The Doppler effect can be observed for any type of wave; Water wave, sound wave, light wave, etc.

Let f_o = frequency heard by observer & f_s = frequency emitted by source

Let v_o , v and v_s respectively Velocity of observer, sound wave & source

The observed frequency due to Doppler Effect is

$$f_o = f_s \left(\frac{v \pm v_o}{v \mp v_s} \right)$$

"Upper" signs (i.e. $+v_o$ & $-v_s$) refer to motion of one towards other.

"Lower" signs (i.e. $-v_o$ & $+v_s$) refer to motion of one away from other.

Characteristics of Waves

The characteristics of waves are important in determining the size of waves, the speed at which they travel, how they break on shore and much more.

Examples

① Reflection of Waves:

Whenever a travelling wave reaches a boundary, part or all of the wave bounces back. This phenomenon (rebounding of wave from a surface) is called reflection.



2) Refraction of wave

It is the change in direction of wave passing from one medium to another caused by its change in speed.

3) Diffraction of wave

→ It is the spreading of waves around obstacles.

→ Diffraction takes place with sound, with electromagnetic radiation, such as light, X-rays & gamma rays

4) Interference of wave

The net effect of combination of two or more wave trains moving on intersecting or coincident paths.

Interference also occurs between two wave trains moving in the same direction but having different wavelengths or frequencies.

A pulsating frequency, called a beat, results when the wavelength are slightly different.

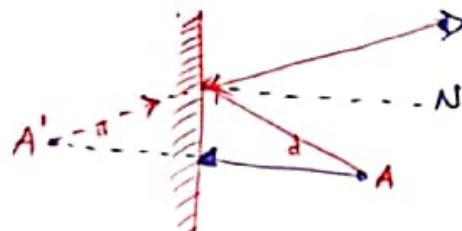
Image formation by thin lenses and mirrors

→ Images Formed by plane mirrors

If the reflecting surface of the mirror is flat, we call this type of

mirror as plane mirror.

→ Light always has regular reflection on plane mirrors.



* We have to see the rays coming from the object to see it. If the light first hits the mirror and then reflects with the same angle, the extensions of the reflected rays are focused at one point behind the mirror. We see the coming rays as if they are coming from behind of the mirror.

→ At point A' image of the point is formed and we call this image Virtual Image which means not real.

The distance of image of the mirror = distance of object to the mirror

→ Images formed by lenses :- Lenses are commonly used to form images by refraction in optical instruments such as cameras, telescopes and microscopes.

A lens is an optical system with two refracting surfaces.

The two types of lenses are

1) Convex lenses

2) Concave lenses.

- * **Wave length (λ):-** distance b/w any two consecutive points which are in phase.
- * **Period (T):-** is the time taken by a wave to move one wave length
- * **frequency(f):-** number of oscillations performed per unit time
- * **Speed (v):** is constant in a medium provided the medium is homogeneous

$$V = \lambda f$$

Types Of Waves

- * Based on the need of material medium for its propagation \nwarrow **Electromagnetic**

- 1) **Mechanical Waves**: are waves produced by oscillation of particles of a mechanical medium and need medium for propagation

Ex. Water waves, Sound waves, wave in strings etc

All mechanical wave requires

- ✓ some source of disturbance
- ✓ a medium that can be disturbed and
- ✓ physical medium through which elements of medium can influence each other

- 2) **Electromagnetic (EM) Waves**: are produced by accelerated charged particles and can propagate through both material medium & Vacuum.

Ex light, radio & TV waves, microwaves, X-rays etc

All EM wave in Vacuum propagate with Speed $C = 3 \times 10^8 \text{ m/s}$

- * Based on the way they are propagating $\begin{array}{c} \rightarrow \text{Transverse} \\ \leftarrow \text{Longitudinal} \end{array}$

- 1) **Transverse Wave**: Where particles of the disturbed medium oscillate perpendicular to the direction of wave motion.

Ex. Water waves, Waves on strings ~~& most all~~ EM waves.

Sinusoidal graphs can represent this motion.

- 2) **Longitudinal Wave**: is a wave where particles of the disturbed medium oscillate parallel to the direction of wave motion.

Ex Sound wave

3) Conversion of Units

To convert a quantity from one unit to another multiply by conversions factors

Ex

<u>Quantity</u>	<u>From</u>	<u>To</u>	<u>Operation</u>
Length	inch (in)	m	(inch) $\times 0.0254$
	foot (ft)	m	(foot) $\times 0.3048$
	mile (mi)	m	(mile) $\times 1609.34$
<u>Mass</u>	pound (lb)	kg	(pound) $\times 0.4536$
	metric ton (t)	kg	(ton) $\times 1000$
	ounce	kg	(ounce) $\times 0.02835$
<u>Volume</u>	litre (l)	m^3	(litre) $\times 0.001$
	gallon (gal)	m^3	(gallon) $\times 0.00379$
Temperature	Fahrenheit (F)	K	$(F - 32) \times \frac{5}{9} + 273.15$
	Celsius (C)	K	$C + 273.15$

Example: 1) $0.02 \text{ in} \rightarrow \text{m}$

Solution $0.02 \text{ in} = 0.02 \times 0.0254 \text{ m} = 0.000508 \text{ m} = \underline{\underline{5.08 \times 10^{-4} \text{ m}}} \text{ or } \underline{\underline{0.503 \text{ mm}}}$

2) Honda fit weights about 2,500 lb to kg

$$\text{Solt} \quad 2,500 \times 0.4536 \\ = \underline{\underline{1134.0 \text{ kg}}}$$

1.2 Uncertainty in Measurement and Significant Digits

Uncertainty - gives the range of possible values of measure and WIC covers true value of measure

All measurements always have some uncertainty.

Errors fall in two categories

1) Systematic Error: Errors resulting from measuring devices being out of calibration

2) Random Error: Resulting in the fluctuation of measurements of the same quantity about the average.

④ Uncertainty in a scale measuring device is equal to the smallest increment divided by 2

$$G_x = \frac{\text{Smallest increment}}{2}$$

Example: Meter stick (scale device) $\rightarrow G_x = \frac{1 \text{ mm}}{2} = 0.5 \text{ mm} = \underline{\underline{0.05 \text{ cm}}}$

⑤ Uncertainty in a digital measuring device is equal to smallest increment

$$G_x = \text{Smallest increment}$$

Example: A reading from digital balance (digital device) is 5.7513 Kg therefore

$$G_x = 0.0001$$

Special Online Tutorial General Physics

1.1 Physical Quantities and Measurement

Physical Quantity :- is a quantifiable or assignable property ascribed to a particular phenomenon or body.

Measurement :- is act of comparing a physical quantity with certain standard.

1. physical quantities

A) Basic physical quantities :- We cannot be expressed in terms of any other physical quantity
Example : length, mass and time

B) Derived physical quantities :- can be expressed in terms of fundamental quantities
Example : Area, Volume, Density

④ Measurements of physical quantities are expressed in terms of Units
Ex Length in meters or kilometers

2. SI Units: Basic and Derived Units

SI → International System of Units

Dimensions

7 → Basic quantities and their SI Unit

1. Length → L → meter (m) → L
2. Mass → m → kilogram (kg) → M
3. Time → t → Second (s) → T
4. Temperature → T → Kelvin (K) → Θ
5. Electric Current → I → ampere (A) → I
6. Amount of Substance → N → mole (N) → L
7. Luminous Intensity → F → candela (Cd) → J

Derived quantities, their SI Units & dimensions

Property	Symbol	Unit	Dimension
Force	F	newton (N)	$\text{kg} \cdot \text{m/s}^2$
Speed	V	m/s	m/s
pressure	P	Pascal (pa)	$\text{kg/m}^2 \text{ (force per unit area)}$
Energy	E	Joule (J)	$\text{kg m}^2/\text{s}^2$
Power	W	watt (W)	$\text{kg m}^2/\text{s}^3$

1.3 Vectors: Composition and Resolution

Scalar: is a quantity that is completely specified by a no. and Unit

- it has magnitude but not direction

Ex mass, time, Volume, Speed etc

Vector: is a quantity that has both specified by a magnitude & direction.

Ex displacement, Velocity, acceleration, momentum etc.

Vector Representation

A) Algebraic Method: Vectors are represented algebraically by a letter (or symbol) with an arrow at its head

Eg Velocity $\rightarrow \vec{V}$, momentum $\rightarrow \vec{P}$

Magnitude of a Vector is a positive scalar b
Written as either $|A|$ or A

Geometric Method

Eg. $\vec{A} + \vec{B} \Rightarrow$ it means beginning of vector \vec{A} to end of another vector \vec{B}

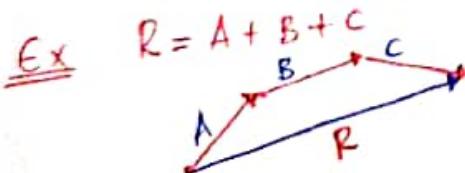
* A Vector changes if its magnitude or direction or if both magnitude and direction change.

Vector Addition

Graphical Method

parallelogram Method

A) Graphical method: can be added by joining their head to tail and in any order their resultant vector is the vector drawn from the tail of the first vector to head of the last vector

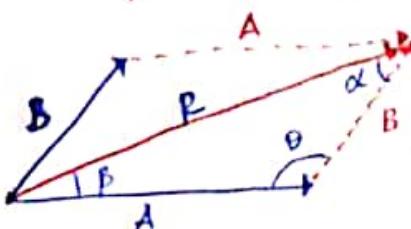


* A single vector that is obtained by adding two or more vectors is called Resultant Vector.

B) parallelogram method

1) Cosine law: $R = \sqrt{A^2 + B^2 - 2AB \cos \theta}$

2) Sine law: $\frac{\sin \theta}{R} = \frac{\sin \alpha}{A} = \frac{\sin \beta}{B}$



where

θ = angle b/w Vector A and B

R = Resultant

$$\textcircled{1} \text{ Measurement} = X_{\text{best}} \pm 6x$$

Where X_{best} = best estimate of measurement

$6x$ = Uncertainty (error) in measurement.

1.2. Significant digits

→ If zero has a non-zero digit anywhere to its left, then zero is significant
Otherwise it is not

Eg → 7.00 has 3 significant figures

→ 0.0007 has only 1 significant figure

→ 1.0007 has 5 sf

→ 300 - Not well defined, Rather $3 \times 10^2 \rightarrow$ has 1 sf or $3.00 \times 10^2 \rightarrow$ has 3 sf

$\textcircled{2}$ When writing numbers, zeros used only to help in locating the decimal point are not significant.

Rules for Significant figures

Rule 1 → When approximate numbers are multiplied/divided, the no. of significant digits in the final answer is the same as the no. of significant digits in the least accurate of factors

$$\text{Ex: } X = \frac{45}{(3.21 \text{ m}) \times (2.00 \text{ m})} = \underline{\underline{6.97015 \text{ N/m}}}$$

→ Least significant factor is 45 has only two digits
so the answer should be

$$X = 7.0 \text{ N/m}$$

Rule 2 → When approximate no. are added or subtracted, the no. of significant digits should equal the smallest no. of decimal places of any term in the sum or difference

$$\text{Ex: } \underline{\underline{9.65 \text{ cm}}} + \underline{\underline{8.4 \text{ cm}}} - \underline{\underline{0.89 \text{ cm}}} = 15.16 \text{ cm}$$

⇒ It should be → 15.2 cm

In general to determine significant digits in a given number

1. All non-zero numbers are significant

2. Zeros within a no. are always significant

3. Zeros that do nothing but set the decimal point are not significant Eg 0.000098 & 0.98 has 2 significant

4. Zeros that aren't needed to hold the decimal points are significant Eg. 4.00 has 3 significant

5. Zeros that follow a number may be significant

CHAPTER- REVIEW QUESTION

1. How would the period of a simple pendulum be affected if it were located on the moon instead of the earth?

Solution

The time period of Simple pendulum is $T = 2\pi\sqrt{\frac{l}{g}}$. The time period is inversely proportional to acceleration due to gravity.

Time period could increase by \sqrt{G} when compared to earth.

Hence, pendulum should swing slower and the frequency will also be on the lower side.

2. What effect would the temperature have on the time kept by a pendulum clock if the pendulum rod increases in length with an increase in temperature?

Solution

→ A major source of error in pendulum clocks is in thermal expansion. The pendulum rod changes in length slightly with change in temperature, causing changes in the rate of the clock.

→ An increase in temperature causes the rod to expand, making the pendulum longer, so its period increases and the clock loses time.

3. What kind of graph would result if the period T were graphed as a function of the square root of the length l .

Solution

We are talking of a simple pendulum so period $T = 2\pi\sqrt{\frac{l}{g}}$

• $\left(\frac{2\pi}{\sqrt{g}}\right)$ is constant $\rightarrow \left(\frac{2\pi}{\sqrt{g}}\right)\sqrt{l}$
for a given location.

So

We can write $T = k\sqrt{l}$ where $k = \frac{2\pi}{\sqrt{g}}$ is constant.

→ Thus, The graph of the period T , as a function of the square root of the length l , would be a straight line with slope

$$k = \frac{2\pi}{\sqrt{g}}$$

A lens is a part of transparent thick glass which is bounded by two spherical surfaces. It is an optical device through which the rays of the light converge or diverge before transmitting.

Convex lenses: Converging lenses thickest at their center and converge a beam of parallel light to real focus.

Concave lenses: Diverging lenses thinnest at their center and diverge a beam of parallel light from virtual focus.

The distance from the focal point to the lens is called focal ~~length~~ length (f).

The equation that relates object and image distances for a lens is identical to the mirror equation

$$\frac{1}{s_o} + \frac{1}{s_i} = \frac{1}{f}$$

Magnification is defined as the ratio of image height (h_i) to object height (h_o) or ratio of image distance (s_i) to object distance (s_o).

$$m = \frac{h_i}{h_o} = \frac{s_i}{s_o}$$

Generally the image formed by a convex lens has the following features.

→ If an object is brought close to the lens, the size of image keeps on increasing.

→ As it goes more close to the lens, the image all the more enlarged.

The images formed will be diminished inverted images, small sizes inverted images, enlarged inverted images, and enlarged erect images. In concave lens there is a possibility of getting real as well as an inverted image.

4) Find a Unit Vector in the direction of resultant Vectors

$$A = 2i - 3j + k$$

$$B = i + j + 2k$$

$$C = 3i - 2j + 4k$$

Solution

$$\vec{A} = 2i - 3j + k$$

$$|A| = \sqrt{2^2 + (-3)^2 + (1)^2}$$
$$= \sqrt{4 + 9 + 1} = \underline{\underline{\sqrt{14}}}$$

$$A_{un} = \frac{\vec{A}}{|A|}$$

$$\vec{A}_{un} = \frac{2i - 3j + k}{\sqrt{14}} = \underline{\underline{\frac{2}{\sqrt{14}}i - \frac{3}{\sqrt{14}}j + \frac{1}{\sqrt{14}}k}}$$

$$\vec{B} = i + j + 2k$$

$$\rightarrow |B| = \sqrt{1^2 + 1^2 + 2^2}$$

$$\text{So } \vec{B}_{un} = \frac{\vec{B}}{|B|} = \underline{\underline{\frac{i + j + 2k}{\sqrt{6}}}}$$

$$\vec{B}_{un} = \underline{\underline{\frac{1}{\sqrt{6}}i + \frac{1}{\sqrt{6}}j + \frac{2}{\sqrt{6}}k}}$$

$$\vec{C} = 3i - 2j + 4k$$

$$\vec{C}_{un} = \frac{\vec{C}}{|C|} \quad |C| = \sqrt{3^2 + (-2)^2 + 4^2}$$
$$=$$

Finish it

(9)

CHAPTER - 3

FLUID MECHANICS

Fluid

mechanics is the branch of physics concerned with the mechanics of fluids in motion (fluid dynamics) or at rest (fluid statics) & forces on them.

→ a fluid is a substance that continually deforms (flows) under an applied shear stress, or external force.

Fluids are a phase of matter include liquids and gases.

Properties of Bulk Matter

a solid may be thought of as having a definite shape and volume, it's possible to change its shape and volume by applying external forces.

→ A sufficiently large force will permanently deform or break an object, but otherwise, when the external forces are removed, the object tends to return to its original shape and size is called elastic behaviour.

Elastic materials are materials that regain their original shape and size when the deforming force is removed.

Elastic deformation is a reversible deformation by a force applied within the elastic limit.

→ Beyond elastic limit, a force applied on an object causes permanent and irreversible deformation called plastic deformation.

Plastic materials do not regain their original shape and size when the deforming force is removed.

The elastic properties of solid materials are described in terms of stress & strain

Stress: is the force per unit area that is causing some deformation

It has SI unit N/m^2 called the pascal (pa), the same as unit of pressure

$$\boxed{\text{Stress} = \frac{F}{A}}$$

Strain: measures the amount of deformation by applied stress and defined as the change in configuration of a body divided by its initial configuration.

strain is Unit less quantity.

$$\text{Strain} = \frac{\text{Change in Configuration}}{\text{Initial Configuration}}$$

There are 3 kinds of strains

- 1) Tensile strain
- 2) shear stress and strain
- 3) Volume stress and strain

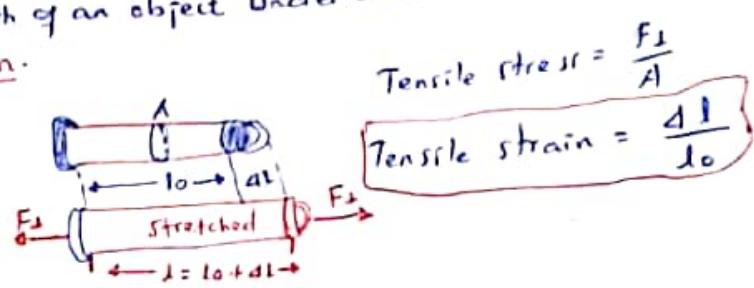
1. Tensile strain

$$\text{Tensile stress} = \frac{\text{the ratio of the force magnitude}}{\text{cross-sectional area}} = \frac{F_1}{A}$$

* The fractional change in length of an object under a tensile stress is called the tensile strain.



(a) A bar in tension

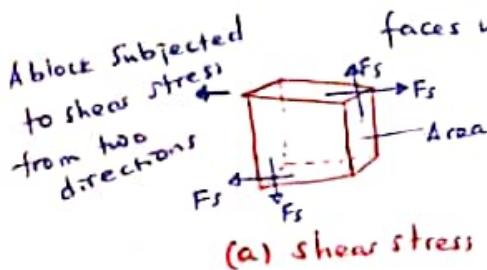


$$\text{Tensile stress} = \frac{F_1}{A}$$

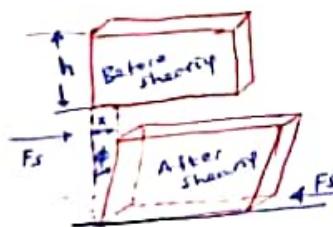
$$\text{Tensile strain} = \frac{l - l_0}{l_0}$$

2. Shear stress and strain

Shear stress - When an object is subjected to a force parallel to one of its faces while the opposite face is held fixed by another force.



(a) shear stress



(b) shear strain

→ Shear strain is defined as the ratio $\frac{x}{h}$, where x is the horizontal distance that the sheared face moves and h is the height of the object.

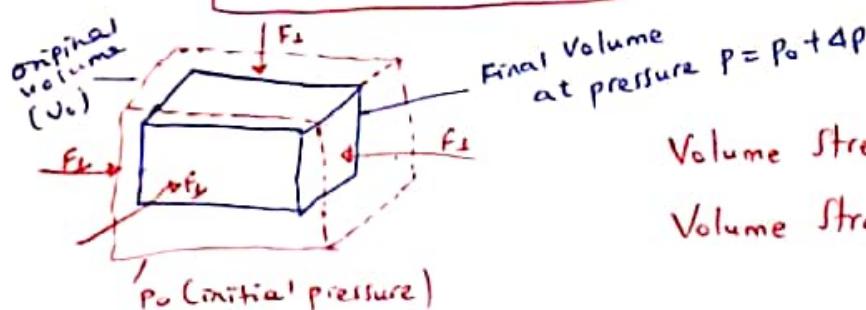
3. Volume stress and strain

Volume Stress is a stress which causes volume deformation on an object and defined as the ratio of change in the magnitude of applied force ΔF to the surface A

$$\text{Volume stress} = \frac{\Delta F}{A}$$

Volume Strain is the fraction change in Volume that is - the change in Volume, ΔV divided by original Volume, V_0

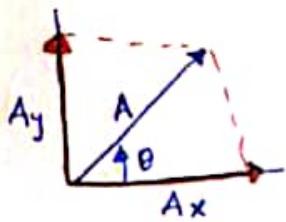
$$\text{Volume strain} = \frac{\Delta V}{V_0}$$



$$\text{Volume stress} = \Delta P$$

$$\text{Volume strain} = \frac{\Delta V}{V_0}$$

3.3 Components of Vector



$$\cos \theta = \frac{Ax}{A} \rightarrow Ax = A \cos \theta \quad \text{x component of } A$$

$$\sin \theta = \frac{Ay}{A} \rightarrow Ay = A \sin \theta \quad \text{y component of } A$$

Resultant $\rightarrow A = Ax + Ay$

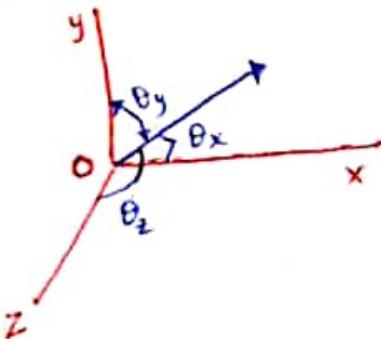
Magnitude of resultant $\rightarrow A = \sqrt{Ax^2 + Ay^2}$

→ for 3 dimension

x, y, z

$$\text{Resultant } R = Rx + Ry + Rz$$

$$\text{Magnitude } R = \sqrt{Rx^2 + Ry^2 + Rz^2}$$



$$\cos \theta_x = \frac{Rx}{R} \Rightarrow \theta_x = \cos^{-1}\left(\frac{Rx}{R}\right) \quad \begin{matrix} \text{x direction} \\ \text{of cosine} \end{matrix}$$

$$\cos \theta_y = \frac{Ry}{R} \Rightarrow \theta_y = \cos^{-1}\left(\frac{Ry}{R}\right) \quad \begin{matrix} \text{y direction} \\ \text{of cosine} \end{matrix}$$

$$\cos \theta_z = \frac{Rz}{R} \Rightarrow \theta_z = \cos^{-1}\left(\frac{Rz}{R}\right) \quad \begin{matrix} \text{z direction} \\ \text{of cosine} \end{matrix}$$

3.4 Unit Vector

- * A unit vector is a vector that has magnitude of one and
 - It is dimensionless
 - It is sole purpose to point a given vector in specified direction.
 - It is usually denoted by with a "hat"

$$A = A\hat{u}$$

Any vector can be expressed in terms of unit vectors

2-dimension

$$A = Ax\hat{i} + Ay\hat{j}$$

3D

$$A = Ax\hat{i} + Ay\hat{j} + Az\hat{k}$$

Addition Let $\vec{A} = Ax\hat{i} + Ay\hat{j} + Az\hat{k}$

$$\vec{B} = Bx\hat{i} + By\hat{j} + Bz\hat{k}$$

$$\vec{A} + \vec{B} = (Ax + Bx)\hat{i} + (Ay + By)\hat{j} + (Az + Bz)\hat{k}$$

Finding a Unit Vector

Consider any vector

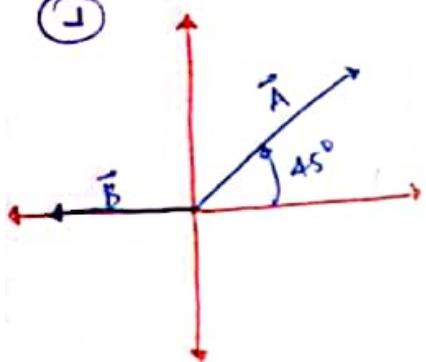
$$\vec{r} = xi + yj + zk$$

The Unit Vector \hat{r} in the same direction is simply vector \vec{r} divided by its magnitude r .

$$\text{Unit vector in the same direction} \quad \hat{r} = \frac{\vec{r}}{r} = \frac{xi + yj + zk}{\sqrt{x^2 + y^2 + z^2}} = \frac{x}{r}\hat{i} + \frac{y}{r}\hat{j} + \frac{z}{r}\hat{k}$$

Chapter Review question / solution /

(1)



find a) magnitude & direction $\vec{A} + \vec{B}$
b) magnitude and direction of $\vec{A} - \vec{B}$

Solution

$$\vec{A} = Ax\hat{i} + Ay\hat{j} \quad Ax = A \cos \theta \quad Ay = A \sin \theta$$

Given
 $A = 8 \text{ unit}, \theta_1 = 45^\circ$
 $B = 8 \text{ unit}, \theta_2 = 0^\circ$

$$\text{So } Ax = 8 \cos 45^\circ = 8 \times \frac{\sqrt{2}}{2} = 4\sqrt{2}$$

$$Ay = 8 \sin 45^\circ = 8 \cdot \frac{\sqrt{2}}{2} = 4\sqrt{2}$$

$$\vec{B} = Bx\hat{i} + By\hat{j}$$

$$Bx = B \cos \theta_2 = -8 \cos 0^\circ = -8 \times 1 = -8$$

$$By = B \sin \theta_2 = -8 \sin 0^\circ = -8 \times 0 = 0$$

So Resultant \vec{R}

$$A = Ax\hat{i} + Ay\hat{j} = 4\sqrt{2}\hat{i} + 4\sqrt{2}\hat{j}$$

$$B = Bx\hat{i} + By\hat{j} = -8\hat{i} + 0\hat{j} = -8\hat{i}$$

$$\begin{aligned} \vec{A} + \vec{B} &= (Ax + Bx)\hat{i} + (Ay + By)\hat{j} \\ &= (4\sqrt{2} - 8)\hat{i} + 4\sqrt{2}\hat{j} \\ &= (-2.3)\hat{i} + 5.7\hat{j} \end{aligned}$$

$$\boxed{A + B = -2.3\hat{i} + 5.7\hat{j}}$$

$$4\sqrt{2} = 5.656$$

$$\approx 5.7$$

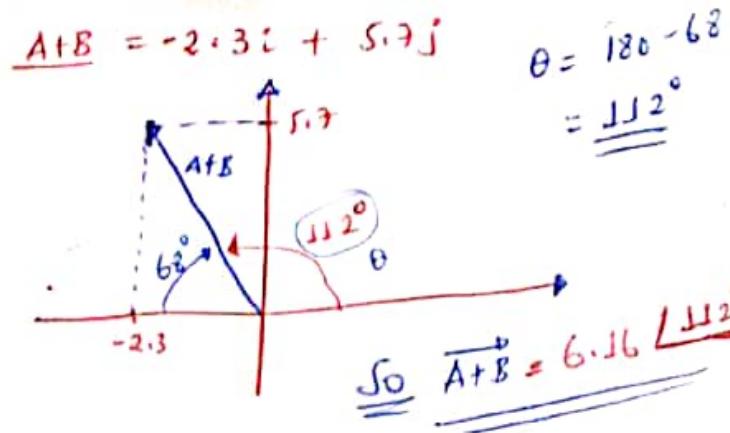
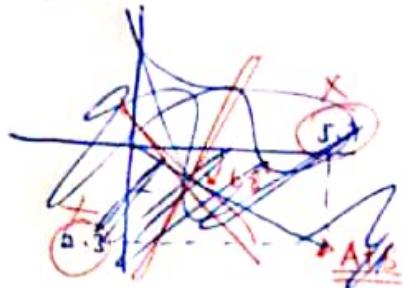
$$\text{magnitude of } A+B = \sqrt{(-2.3)^2 + (5.7)^2} = \sqrt{37.98} = 6.16$$

$$\text{Direction of } A+B \Rightarrow \alpha = \tan^{-1}\left(\frac{5.7}{-2.3}\right) = -68^\circ$$

(6)

$$\text{Lpso } \theta = 180 - \alpha = 180 - 68^\circ = 112^\circ$$

Graph of A+B



- ③ If $A = 6i - 8j$, $B = -8i + 3j$, $C = 2i + 19j$
find a & b such that $aA + bB + C = 0$.

Soln

$$aA = 6ai - 8aj$$

$$bB = -8bi + 3bj$$

$$C = 2i + 19j$$

Given $aA + bB + C = 0i + 0j$

$$(6a - 8b + 26)i + (-8a + 3b + 19)j = 0i + 0j$$

So

$$6a - 8b + 26 = 0 \quad \dots \textcircled{1}$$

$$-8a + 3b + 19 = 0 \quad \dots \textcircled{2}$$

$$6a - 8b = -26 \quad \dots \text{divide by } \textcircled{2}$$

$$-8a + 3b = -19$$

$$(3a - 4b = -13) \times 3$$

$$(-8a + 3b = -19) \times 4$$

$$9a - 12b = -39$$

$$-32a + 12b = -76$$

$$\frac{-23a}{-23} = \frac{-115}{-23}$$

$$a = \frac{-115}{-23} = \frac{115}{23}$$

$$a = \underline{\underline{5}}$$

Put a into equation

$$-8a + 3b = -19$$

$$-8(\underline{\underline{5}}) + 3b = -19$$

$$-40 + 3b = -19$$

$$3b = -19 + 40$$

$$3b = 21$$

$$b = \frac{21}{3}$$

$$b = \underline{\underline{7}}$$

So, The Value of

$$a = \underline{\underline{5}} \quad b = \underline{\underline{7}}$$

(2)

Example

A sample of an unknown material weighs 300N in air & 200N when submerged in alcohol (solute) with a density of $0.7 \times 10^3 \text{ kg/m}^3$. What is density of material?

Solution

Given

$$W_{\text{air}} = 300\text{N}$$

$$W_{\text{alcohol}} = 200\text{N}$$

$$\rho_{\text{alcohol}} = 0.7 \times 10^3 \text{ kg/m}^3$$

$$\rho_{\text{material}} = ? (\rho_0)$$

$$F_{\text{buoyant}} = W_{\text{air}} - W_{\text{alcohol}}$$

$$= 300 - 200$$

$$= 100\text{N}$$

$$\frac{W_{\text{air}}}{F_{\text{buoyant}}} = \frac{\rho_0}{\rho_{\text{alcohol}}} \Rightarrow \rho_0 = \frac{W_{\text{air}} \times \rho_{\text{alcohol}}}{F_{\text{buoyant}}}$$

$$= \frac{(0.7 \times 10^3) \times (300)}{100}$$

$$\rho_0 = \underline{\underline{0.1 \times 10^3 \text{ kg/m}^3}}$$

Moving Fluids & Bernoulli equation

- If the flow is steady, then the velocity of the fluid particles at any point is a constant with time. The various layers of the fluid slide smoothly past each other. This is called Streamline or Laminar flow.
- Turbulent flow is the irregular movement of particles in a fluid and results in loss of energy due to internal friction b/w neighboring layers of the fluid, called Viscosity.
- * Factors affecting laminar flow are density, compressibility, temperature and viscosity.

Assumptions

- * The fluid is non-viscous → There is no internal friction b/w adjacent layers
- * The flow is steady → The velocity of fluid at each point remains constant
- * The fluid is incompressible → density of fluid is constant
- * The flow is irrotational → the fluid has no angular momentum about any point.

Equation of Continuity

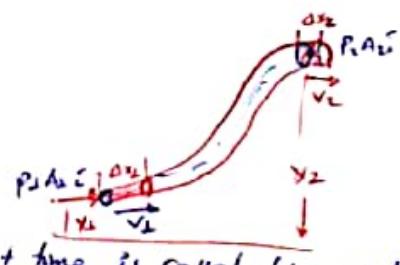
Equation of continuity expresses conservation of mass for an incompressible fluid flowing in a tube. It says « the amount (either mass or volume) of fluid flowing through a cross section of tube in a given time interval must be the same for all cross-sections. Or the product of the area and the fluid speed at all points along a tube is constant for an incompressible fluid.

$$AV = A_1V_1 = A_2V_2$$

$$\boxed{\text{flow rate} = \frac{\text{Volume}}{\text{time}} = AV = \text{constant.}}$$

→ When Cross sectional Area is decreased then the flow rate increases

The product AV , where A is the dimensions of Volume per unit time is called flow rate



Atmospheric pressure is the pressure due to weight of atmosphere exerted on the surface of Earth.

→ Atmospheric pressure decrease with increase in altitude (due to decrease in density of air)

Gauge pressure is the difference in pressure b/w a system and surrounding atmosphere

$$P_{\text{gauge}} = P_{\text{system}} - P_{\text{atmosphere}}$$

Gauge pressure is relative to atmospheric pressure

positive for pressure above atmospheric pressure
negative for below it

Absolute pressure is the total pressure

Cannot be negative Pa

$$P_{\text{absolute}} = P_{\text{gauge}} + P_{\text{atmosphere}}$$

→ Smallest absolute pressure is zero. Thus, smallest possible gauge pressure

$$\text{is } P_{\text{gauge}} = -P_{\text{atmosphere}}$$

Example

A submerged wreck is located 18.3m beneath the surface of the ocean off the coast of South Florida. Determine

a) P_{gauge} b) P_{abs}

(Note → density of sea water is 1025 kg/m^3)

Solution

$$\text{a) } P_{\text{gauge}} = \rho gh = (1025 \text{ kg/m}^3) (9.8 \text{ m/s}^2) (18.3 \text{ m}) = 1.83 \times 10^5 \frac{\text{N}}{\text{m}^2}$$

$$P_{\text{gauge}} = 1.83 \times 10^5 \frac{\text{N}}{\text{m}^2} = 183 \text{ kPa}$$

$$\text{b) } P_{\text{abs}} = P_{\text{gauge}} + P_{\text{atm}}$$

$$= (1.83 \times 10^5 + 1.013 \times 10^5) \frac{\text{N}}{\text{m}^2}$$

$$= 2.84 \times 10^5 \frac{\text{N}}{\text{m}^2} = 284 \text{ kPa}$$

Density and pressure in static fluids

Density (ρ) is the quantity of mass (m) per Unit Volume (V) of a body with SI unit kg/m^3 and given by $P = \frac{m}{V}$

Specific gravity (SG) is the ratio of density of a substance to the density of another substance which is taken as standard.

→ The density of pure water at 4°C = $1.0 \times 10^3 \text{ kg/m}^3$ - taken as standard

- The SG is dimensionless quantity and the same in any system of measurement

Example: The density of aluminum is $2.7 \times 10^3 \text{ kg/m}^3$

$$\therefore \text{the SG of Al is } SG = \frac{2.7 \times 10^3 \text{ kg/m}^3}{1.0 \times 10^3 \text{ kg/m}^3} = \underline{\underline{2.7}}$$

Example: A solid sphere made of wood has a radius of 0.1m . The mass of sphere is 1.0 kg . Determine a) density b) SG

Solution: The volume of sphere wood is $V = \frac{4}{3}\pi r^3$

Given: $r = 0.1\text{m}$ $m = 1\text{ kg}$

$$= \frac{4}{3}\pi(0.1)^3 = \underline{\underline{4.18 \times 10^{-3} \text{ m}^3}}$$

So a) density $\rightarrow P = \frac{m}{V} = \frac{1\text{ kg}}{4.18 \times 10^{-3} \text{ m}^3} = \underline{\underline{239 \text{ kg/m}^3}}$

b) $SG \rightarrow SG = \frac{\text{density of wood}}{\text{density of water}} = \frac{239 \text{ kg/m}^3}{1 \times 10^3 \text{ kg/m}^3}$

$$SG = \underline{\underline{0.239}}$$

Pressure: is the ratio of force acting perpendicular to surface Area (A) on which the force acts.

- SI Unit N/m^2 , called pascal (Pa)

- Another pressure unit is atmosphere (atm) equal to 101.3 kPa which is average pressure exerted by the Earth's atm at sea level

$$P = \frac{F}{A}$$

→ pressure produced by the column of fluid of height h and density ρ is given by $P_{\text{fluid}} = \rho gh$

Note that

- All points at same level in a fluid have same pressure
- Fluid pressure increase with increase in the depth of fluid
- Fluid pressure does not depend on the shape of container

Elasticity Moduli:

The stress will be proportional to the strain if the stress is sufficiently small. In this regard, the proportionality constant known as elastic modulus depends on the material being deformed and on the nature of deformation.

$$\boxed{\text{Stress} = \text{elastic modulus} \times \text{strain}}$$

- There are 3 types of elastic modulus

1. Young's Modulus: is the ratio of tensile stress to tensile strain.

It measures the resistance of a solid to a change in its length and typically used to characterize a rod or wire stressed under either tension or compression.

$$\boxed{Y = \frac{\text{tensile stress}}{\text{tensile strain}} = \frac{F/A}{\Delta L/L_0}}$$

Y - has unit of force per Unit area

$$\boxed{Y \Rightarrow F/A = N/m^2}$$

2. Shear Modulus: it is the measure of the resistance to motion of the planes within a solid parallel to each other.

A material having large shear modulus is difficult to bend.

$$\boxed{S = \frac{\text{Shear Stress}}{\text{Shear Strain}} = \frac{\Delta F/A}{X/h}}$$

Its SI units pascal

3. Bulk Modulus: it measures the resistance of solids or liquids to changes in their volume

A material having a large bulk modulus doesn't compress easily.

$$\boxed{B = \frac{\text{Volume Stress}}{\text{Volume Strain}} = \frac{-\Delta F/A}{\Delta V/V_0} = \frac{-\Delta P}{\Delta V/V_0}}$$

* a negative sign is included in this defining equation, so that B is always positive.

* An increase in pressure (+ve ΔP) causes a decrease in volume negative (ΔV) and vice versa.

- Strain Energy is the energy stored in a stretched wire.

If X is due to applied force F ,

$$\boxed{\text{Strain Energy} = \frac{1}{2} K X^2}$$

Example

Suppose that the tension in the cable is 940 N as the actor reaches the lowest point. What diameter should a 50-m long steel wire have if we do not want it to stretch more than 0.5 cm under these conditions?

Solution

$$F = 940 \text{ N} \quad \text{from definition of Young modulus}$$

$$l_0 = 50 \text{ m}$$

$$\Delta l = 0.5 \text{ cm} = 0.005 \text{ m} \quad Y = \frac{F_l}{A} \rightarrow A = \frac{F_l}{Y \Delta l}$$

$$d = ?$$

Since we are asked diameter we can get it from Area

$$\text{Also } Y = 20 \times 10^{10} \text{ N/m}^2 \text{ -- for steel wire}$$

$$\text{So } A = \frac{(940 \text{ N}) (50 \text{ m})}{(20 \times 10^{10} \text{ N/m}^2) (0.005 \text{ m})}$$

$$A = 9.4 \times 10^{-6} \text{ m}^2$$

$$\text{Because of radius of wire} \rightarrow A = \pi r^2$$

$$r = \sqrt{\frac{A}{\pi}} = \sqrt{\frac{9.4 \times 10^{-6} \text{ m}^2}{\pi}} = 1.7 \times 10^{-3} \text{ m} = 1.7 \text{ mm}$$

$$\text{So, } d = 2r = 2(1.7 \text{ mm}) = 3.4 \text{ mm}$$

Activity

A solid brass sphere is initially surrounded by air, and the air pressure exerted on it is $1.0 \times 10^5 \text{ N/m}^2$. The sphere is lowered into the ocean to a depth where the pressure is $2.0 \times 10^7 \text{ N/m}^2$. The volume of sphere in air is 0.50 m^3 . By how much does this volume change once the sphere is submerged?

Solution From definition of bulk modulus

$$B = -\frac{\Delta P}{\frac{\Delta V}{V_i}} \rightarrow \Delta V = -\frac{V_i \Delta P}{B}$$

Given

$$P_i = 1.0 \times 10^5 \text{ N/m}^2$$

$$P_f = 2.0 \times 10^7 \text{ N/m}^2$$

$$V_i = 0.5 \text{ m}^3$$

$$\Delta V = ?$$

$$B = 6.1 \times 10^{10} \text{ N/m}^2 \text{ for } \underline{\text{Brass}}$$

$$\text{So, } \Delta P = P_f - P_i \approx P_f = 2.0 \times 10^7 \text{ N/m}^2$$

B/c final pressure is much greater than initial pressure

$$\Delta V = -\frac{(0.5 \text{ m}^3)(2.0 \times 10^7 \text{ N/m}^2)}{6.1 \times 10^{10} \text{ N/m}^2}$$

$$\Delta V = -1.6 \times 10^{-4} \text{ m}^3 \rightarrow \text{-ve sign indicates decrease in volume}$$

5) Lead has a greater density than iron, and both are denser than water. Is the buoyant force on a lead object greater than, less than or equal to the buoyant force on an iron object of the same volume?

Solution The buoyant force of a liquid on an object is equal to the weight of liquid displaced by it.

⇒ Since the lead object and iron object have the same volume, both of them displace the same amount of water. Hence buoyant force is the same.

6. When an object is immersed in a liquid at rest, why is the net force on an object in the horizontal direction is equal to zero?

Solution The pressure is the same on points that are at the same level but on opposite sides, so net force along horizontal equals to zero.

7. When water freezes, it expands by about 9.0%. What pressure increase would occur inside your automobile engine block if the water in it froze? (The bulk modulus of ice is $2 \times 10^9 \text{ N/m}^2$)

Solution

$$B = \frac{\Delta P}{\Delta V/V} \rightarrow \Delta P = B \times \frac{\Delta V}{V}$$

Given

$$\Delta V = 9\% V$$

$$\boxed{\Delta V = 0.09 V}$$

$$V_c = V$$

$$= (2 \times 10^9 \text{ N/m}^2) \times \left(\frac{0.09 V}{V} \right)$$

$$\Delta P = 0.18 \times 10^9 \text{ Pa/m}^2$$

$$\Delta P = 1.8 \times 10^{10} \text{ Pa/m}^2$$

=====

8. A 40cm tall glass is filled with water to a depth of 30cm
 A. What is the gauge pressure at the bottom of glass?
 B. What is the absolute pressure at the bottom of glass?

Solution

Given $h = 30 \text{ cm} = 0.3 \text{ m}$ $P_{\text{water}} = 1 \times 10^3 \text{ kg/m}^3$
 $g = 9.81 \text{ m/s}^2$

a) $P_{\text{gauge}} = Pgh = (1000)(9.81)(0.3)$
 $= \underline{\underline{2.9 \times 10^3 \text{ Pa}}}$

b) $P_{\text{absolute}} = P_{\text{gauge}} + P_{\text{atm}}$
 $= 2.9 \times 10^3 \text{ Pa} + 1.01 \times 10^5 \text{ Pa}$

$$P_{\text{absolute}} = \underline{\underline{1.04 \times 10^5 \text{ Pa}}}$$

• 9) calculate the absolute pressure at an ocean depth of 1.0×10^3 m. Assume that the density of the water is $1.025 \times 10^3 \text{ kg/m}^3$ and that $P_{\text{atm}} = 1.01 \times 10^5 \text{ Pa}$

Solution

Given
 $h = 1.0 \times 10^3 \text{ m}$

$$\rho_r = 1.025 \times 10^3 \text{ kg/m}^3$$

$$P_{\text{atm}} \text{ or } P_0 = 1.01 \times 10^5 \text{ Pa}$$

$$P_{\text{absolute}} = ?$$

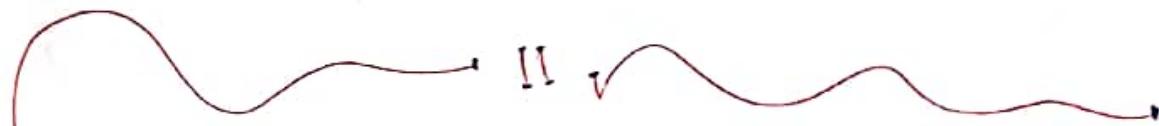
Soln

$$P_{\text{abs}} = P_{\text{atm}} + P_{\text{atm}}$$

$$= \rho g h + P_{\text{atm}}$$

$$= (1.025 \times 10^3 \text{ kg/m}^3) (9.81 \text{ m/s}^2) (1 \times 10^3 \text{ m}) + 1.01 \times 10^5 \text{ Pa}$$

$$\underline{\underline{P_{\text{absolute}} = 1.01 \times 10^7 \text{ Pa}}}$$



!!

END OF CH - 3

CHAPTER - 4

HEAT AND THERMODYNAMICS

Thermodynamics is a science of the relationship b/w heat, work, temperature & energy.
It deals with the transfer of energy from one system to another / from one form to other.

Heat is defined as the flow of energy from one object to another. This flow of energy is caused by a difference in T° . Heat can flow \rightarrow if they are in thermal contact.

Two objects are in thermal equilibrium if they are in close contact that allows either to gain energy from other, but nevertheless no energy transferred.

Experimentally, if object A is in thermal equilibrium with object B, and object B is in thermal equilibrium with object C, then, object A is in thermal equilibrium with object C. \rightarrow This is called the Zeroth law of thermodynamics.

* Thermometers measure Temperature according to well-defined scales of measurement
The three most common T° -scales are Fahrenheit, Celsius and Kelvin.

\rightarrow Temperature scales are created by identifying two reproducible temperatures
The freezing and boiling T° of water at standard atmospheric pressure used.

* Freezing point of water is 0°C and boiling point is 100°C . [degree Celsius]

* Freezing point of water is 32°F and boiling point is 212°F (degree Fahrenheit)

$$* T_F = \frac{5}{9} T_C + 32$$

$$T_K = \frac{5}{9} (T_F - 32) + 273.15$$

$$* T_C = \frac{9}{5} (T_F - 32)$$

$$T_F = \frac{9}{5} (T_C - 273.15) + 32$$

$$* T_K = T_C + 273.15$$

Thermal Expansion

Thermal expansion is the change in size or volume of a given system as its temperature changes. Example Expansion of alcohol, expansion of air

\rightarrow Linear thermal expansion

The increase in length Δl of a solid is proportional to its initial length, l_0 and the change in its temperature ΔT . The proportionality constant is called the coefficient of linear expansion α .

$$\boxed{\Delta l = \alpha l_0 \Delta T} \rightarrow l = l_0 (1 + \alpha \Delta T) \quad \alpha = \frac{l_0}{\Delta l} \Delta T$$

\rightarrow Areal Expansion

$$\Delta A = \beta A_0 \Delta T \Rightarrow A = A_0 (1 + \beta \Delta T) \rightarrow \boxed{\beta = 2\alpha} \quad \text{it has units } \text{K}^{-1}$$

\rightarrow Volume Expansion

$$\boxed{\beta = 3\alpha} \quad \text{coefficient and } (C^\circ)^{-1}$$

3. A 30 kg hammer strikes a steel spike 2.30 cm in diameter. Spike 2.30 cm in diameter while moving with a speed of 20 m/s. The hammer rebounds with speed 10 m/s after impact. What is the average strain in the spike during impact?

Given

$$\begin{aligned}m &= 30 \text{ kg} \\ \Delta t &= 0.11 \text{ s}\end{aligned}$$

$$V_i = 20 \text{ m/s}$$

$$V_f = -10 \text{ m/s} \text{ (rebounded)}$$

$$\text{Strain} = ?$$

Solution

$$\text{Stress} = \frac{F}{A}$$

~~F~~

$$\Delta P = F \cdot \Delta t = m(V_f - V_i)$$

$$\text{Impulse} = \Delta P$$

$$F \cdot \Delta t = m(V_f - V_i)$$

$$F \times 0.11 = 30 (-10 - 20)$$

$$F = \frac{-900}{0.11} = \underline{\underline{8.18 \times 10^3 \text{ N}}}$$

$$\text{Stress} = \frac{8.18 \times 10^3 \text{ N}}{\pi \times \left(\frac{2.3}{2} \times 10^{-2}\right)^2}$$

$$A = \pi \left(\frac{d}{2}\right)^2 = \pi \left(\frac{2.3}{2} \times 10^{-2}\right)^2$$

$$\boxed{\text{Stress} = 1.97 \times 10^7 \text{ N/m}^2}$$

$$\text{Strain} = \frac{\text{Stress}}{\gamma} = \frac{1.97 \times 10^7}{2 \times 10^{11}} = \underline{\underline{9.85 \times 10^{-5}}}$$

4. If the shear stress in steel exceeds about $4 \times 10^8 \text{ N/m}^2$, the steel ruptures. Determine the shear force necessary to

a) shear a steel bolt 1 cm in diameter

b) punch a 1 cm diameter hole in a steel plate 0.5 cm thick

Solution

a) Stress = $\frac{F}{A} \rightarrow \boxed{\text{Force applied} = \text{Stress} \times \text{Area}}$

$$F = 4 \times 10^8 \text{ N/m}^2 \times \pi r^2$$

$$r = \frac{d}{2} = \frac{1}{2} = 0.5 \text{ cm}$$

$$= 4 \times 10^8 \text{ N/m}^2 \times \pi (0.5 \times 10^{-2})^2$$

$$r = \underline{\underline{5 \times 10^{-3} \text{ m}}}$$

$$= \underline{\underline{3.14 \times 10^4 \text{ N}}}$$

b) The area over which shear stress occurs is equal to the circumference of the hole times its thickness

$$\text{Thus, } A = (2\pi r)t = 2\pi (0.5 \times 10^{-2} \text{ m}) (0.5 \times 10^{-2} \text{ m}) = \underline{\underline{1.57 \times 10^{-4} \text{ m}^2}}$$

$$\therefore F = A \times \text{stress}$$

$$= (1.57 \times 10^{-4} \text{ m}^2) (4 \times 10^8 \text{ N/m}^2)$$

$$\boxed{F = 6.28 \times 10^4 \text{ N}}$$

Chapter Questions and problems

1. A 200kN load is hung on a wire having a length of 4.00m, cross-sectional area $0.2 \times 10^{-4} m^2$ and Young Modulus $8 \times 10^{10} N/m^2$ what is increase in length?

Given

$$l_0 = 4 \text{ m}$$

$$A = 0.2 \times 10^{-4} m^2$$

$$Y = 8 \times 10^{10} N/m^2$$

$$m = 200 \text{ kg}$$

$$\Delta l = ?$$

From Young Modulus

$$Y = \frac{F_2}{A} = \frac{F_2 l_0}{\frac{\Delta l}{l_0}} = \frac{F_2 l_0}{\Delta l l_0}$$

$$F_2 = mg$$

Sol.

$$\Delta l = \frac{F_2 l_0}{A Y} = \frac{mg l_0}{A Y}$$

Answer

$$\underline{\underline{\Delta l = 4.91 \text{ mm}}}$$

$$\Delta l = \frac{200 \text{ kN} (9.8 \text{ m/s}^2) (4 \text{ m})}{0.2 \times 10^{-4} m^2 \times 8 \times 10^{10} N/m} \approx \underline{\underline{4.91 \text{ mm}}}$$

2. A steel wire of diameter 1mm can support a tension of 0.2kN. A steel cable to support a tension of 20kN should have diameter of what order of magnitude?

From Young modulus

$$Y = \frac{F_2 l_0}{\Delta l A} \rightarrow A = \frac{F_2 l_0}{\Delta l Y}$$

Given $d_1 = 1 \text{ mm}$

$$F_1 = 0.2 \text{ kN}$$

$$F_2 = 20 \text{ kN}$$

$$d_2 = ?$$

Let A_1 - Cross-sectional Area of steel wire
 A_2 - $\dots \dots \dots$ of steel cable

$$A_1 = \frac{F_2 l_0}{Y d_1} \quad A_2 = \frac{F_2 l_0}{Y d_2} \rightarrow \underline{\underline{S_o}}, \quad \frac{A_2}{A_1} = \frac{\frac{F_2 l_0}{Y d_2}}{\frac{F_2 l_0}{Y d_1}} = \frac{d_1}{d_2}$$

$$\frac{A_2}{A_1} = \frac{F_2}{F_1}$$

$$A_1 = \frac{\pi d_1^2}{4}$$

$$A_2 = \frac{\pi d_2^2}{4}$$

$$\frac{\frac{\pi d_2^2}{4}}{\frac{\pi d_1^2}{4}} = \frac{F_2}{F_1} \rightarrow \frac{d_2^2}{d_1^2} = \frac{F_2}{F_1}$$

$$d_2^2 = d_1^2 \times \frac{F_2}{F_1}$$

$$d_2^2 = (1 \times 10^{-3} \text{ m})^2 \times \frac{20 \text{ kN}}{0.2 \text{ kN}} = 10^{-6} \times 100 = \underline{\underline{10^{-4}}}$$

$$d_2 = \sqrt{10^{-4} \text{ m}^2} = \underline{\underline{10^{-2} \text{ m}}}$$

$$d_2 = \underline{\underline{10 \text{ mm}}}$$

Bernoulli's Equation

- * The sum of pressure, kinetic energy per unit volume, and gravitational potential energy per unit volume has the same value at all points along a streamline.

(This is called Bernoulli's Equation)

$$P_1 + \frac{1}{2} \rho V_1^2 + \rho g h_1 = P_2 + \frac{1}{2} \rho V_2^2 + \rho g h_2$$

ρ = density
 V = Velocity
 P = pressure

Example

Water circulates throughout a house in a hot water heating system. If the water is pumped at a speed of 0.50 m/s through a 4 cm diameter pipe in basement under pressure of 3.03×10^5 Pa. What will be velocity and pressure in a 2.6 cm diameter pipe on the 2nd floor 5m above?

Given

$$V_1 = 0.5 \text{ m/s} \quad V_2 = ?$$

$$h_1 = 0 \text{ m (horizontal)} \quad h_2 = 5 \text{ m}$$

$$d_1 = 4 \text{ cm} = 0.04 \text{ m} \quad d_2 = 2.6 \text{ cm} = 0.026 \text{ m}$$

$$A_1 = \pi r_1^2 = \pi (d_1/2)^2 \quad A_2 = \pi (d_2/2)^2 = \underline{\underline{1.69 \times 10^{-4} \pi}}$$

$$= \underline{\underline{0.0004 \pi}}$$

$$P_1 = 3.03 \times 10^5 \text{ Pa} \quad P_2 = ?$$

Solution

from Equation of Continuity

$$A_1 V_1 = A_2 V_2$$

$$V_2 = \frac{A_1 V_1}{A_2} = \frac{(0.0004 \pi)(0.5)}{1.69 \times 10^{-4} \pi} = \underline{\underline{11.83 \text{ m/s}}}$$

from Bernoulli's Equation

$$\begin{aligned} P_2 &= P_1 + \frac{1}{2} \rho V_1^2 + \rho g h_1 - \frac{1}{2} \rho V_2^2 - \rho g h_2 \\ &= P_1 + \frac{1}{2} \rho (V_1^2 - V_2^2) + \rho g (h_1 - h_2) \\ &= 3.03 \times 10^5 + \frac{1}{2} (1.0 \times 10^3) [0.5^2 - 11.83^2] + (1 \times 10^3) (9.8) [0 - 5] \end{aligned}$$

$$\underline{\underline{P_2 = 1.84 \times 10^5 \text{ Pa}}}$$

CHAPTER-5

Simple Harmonic Motion

5.1.1 Periodic and Oscillatory Motion

When a body repeats its path of motion back and forth about the equilibrium or mean position, the motion is said to be periodic.

Types of Oscillatory motion

There are two types of oscillatory motion

Linear oscillation &
Circular oscillation

Example of Linear oscillation

1. Oscillation of mass spring system
2. Oscillation of fluid column in U-tube
3. Oscillation of floating cylinder
4. Oscillation of body dropped in a tunnel along earth diameter.
5. Oscillation of strings of musical instruments.

Example of Circular motion

1. Oscillation of simple pendulum
2. Oscillation of solid sphere in a cylinder
3. Oscillation of circular ring suspended in air
4. Oscillation of balance wheel of a clock
5. Rotation of earth around the Sun

Oscillatory System

Oscillations are the basic blocks of waves. Oscillatory systems are of two types mechanical and non-mechanical systems.

Mechanical Oscillatory Systems :- in this type of a system a body itself changes its position. For mechanical oscillation two things are especially responsible, inertia and restoring force.

Non-mechanical Oscillatory Systems :- the body itself doesn't change its position but its physical property varies periodically.

Period → (T) :- is the time required to complete one full cycle of vibration or oscillation.

Frequency → (f) :- The frequency is the number of complete oscillations or cycles per unit time.

The frequency of wave is given by
$$f = \frac{1}{T}$$

The first law of thermodynamics

The 1st law of thermodynamics states that "The change in internal energy of a system is equal to the sum of the heat flow into the system and the work done on the system." In equation $\Delta U = Q + W$

ΔU - change in internal energy

$W = P\Delta V$ - Work done on the system

- P - Pressure

- ΔV - Volume

The first law of different thermodynamic sys

Isolated System :- is a system which does not exchange heat with its surroundings and no work is done on the external environment.

$$\Delta U = 0 \text{ or } U = \text{Constant}$$

The internal energy of an isolated system is Constant.

Cyclic process :- Engines Operate in Cycles, in which the system, Example, after periodically returns to its initial state.

Since, the system returns to its initial state, the change in internal energy in one complete cycle is zero.

$$\Delta U = 0 \rightarrow \text{So, } Q = W$$

Isochoric process :- In a constant volume process, the volume of the system stays constant.

$$\text{Consequently, } W = 0 \rightarrow \Delta U = Q$$

→ All the heat entering the system goes into increasing internal energy

Adiabatic process :- The System does not exchange heat with its surroundings, $Q = 0 \rightarrow \Delta U = W$

Isothermal process :- It is a process which involves no change in temperature of the system.

If the process occurs at constant temperature then there is no change in the internal energy of the system so ΔU .

The 1st law for isothermal

$$\Delta U = Q + W \rightarrow 0 = Q + W$$

For ideal gas in isothermal process

$$Q = -W$$

$$W = nRT \ln \left(\frac{V_f}{V_i} \right)$$

Isochoric process :- the expansion or compression occurs at constant pressure. Any work done by the system will result in an increase in volume

The work done on pressure-volume graph is equal to under PV graph

$$\text{For isochoric } W = P\Delta V = P(V_f - V_i)$$

$$\text{1st law of isobaric process} \rightarrow \Delta U = Q + W \text{ or } \Delta U = Q - P\Delta V$$

$$= Q - P(V_f - V_i)$$

Example-1

5000J of heat are added to two moles of an ideal monatomic gas, initially at a temperature of 500K, while the gas performs 7500J of work. What is the final temperature of the gas?

Solution

$$\begin{aligned}\Delta U &= Q + W \\ &= 5000 - 7500 \\ &= -2500 \text{ J}\end{aligned}$$

from equation $\Delta U = nC\Delta T \rightarrow \Delta U = \frac{3}{2}nR\Delta T$

$$\Delta U = \frac{3}{2}nR\Delta T$$

$$-2500 = \frac{3}{2}(2)(8.31) \Delta T$$

$$\underline{\underline{\Delta T = -100 \text{ K}}}$$

$$\begin{aligned}\Delta T &= T_f - T_i \\ -100 \text{ K} &= T_f - 500 \text{ K}\end{aligned}$$

$$\underline{\underline{T_f = 400 \text{ K}}}$$

Example-2

2000J of heat leaves the system and 2500J of work is done on the system.

What is the change in internal energy of the sys?

Soln

$$Q = -2000 \text{ J}$$

$$\underline{\underline{W = 2500 \text{ J}}}$$

$$\Delta U = Q + W$$

$$= -2000 + 2500$$

$$\boxed{\Delta U = 500 \text{ J}}$$

Activity: A 1 mol sample of an ideal gas is kept at 0.0°C during an expansion from 3.0L to 10L

a) How much work is done on the gas during expansion?

Solution

$$W = nRT \ln\left(\frac{V_f}{V_i}\right)$$

$$= (1 \text{ mol}) (8.315 \text{ J/mol.K}) (273 \text{ K}) \ln\left(\frac{10}{3}\right)$$

$$= 0.73 \times 10^3 \text{ J}$$

b) How much energy transferred by heat occurs with the surroundings in this process

$$\Delta U = Q + W$$

~~$\Delta U = 0$~~

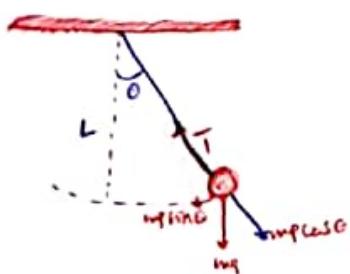
$$Q = W$$

$$\underline{\underline{Q}}$$

$$\underline{\underline{Q = W = 0.73 \times 10^3 \text{ J}}}$$

The Simple Pendulum

A simple pendulum is another mechanical system that exhibits periodic motion.



The force of gravity is the only force that acts on the pendulum.

The pendulum bob moves along a circular arc, rather than back and forth on a straight line.

$$\text{Hooke's law} \rightarrow T = 2\pi \sqrt{\frac{L}{g}}$$

L - length
g - gravity

T - Period

- * Period of simple pendulum does not depend on mass but only length & free fall acceleration.

Eg. A rock swings in a circle. Constant speed on the end on a string, making 50 revolutions in 30 sec. What is frequency and period of this motion?

$$\text{Soln} \quad f = \frac{50 \text{ revs}}{30 \text{ sec}} = 1.67 \text{ rev/sec} = 1.67 \text{ Hz}$$

$$T = \frac{1}{f} = \frac{1}{1.67} = 0.6 \text{ sec}$$

Energy of Simple Harmonic Oscillator

In the absence of friction, the total energy of a block-spring system is constant and equal to the sum of kinetic and potential energies.

$$PE = \frac{1}{2} kx^2 \quad KE = \frac{1}{2} mv^2$$

∴ Total energy of the oscillator performing SHM is

$$E = \frac{1}{2} KA^2$$

- * Energy of SHM is constant & proportional to square of Amplitude.

Wave and Its Characteristics

- * Wave is a disturbance from normal or equilibrium conditions that travels, or propagates, carrying energy and momentum through space without the transport of matter.

- * Pulse is a single disturbance travelling into a medium.

Wave supplies energy to the particles in a medium to set them in motion.

Terminologies in Wave

Crests / Thoughts: are positions in a wave with maximum displacement above/below the equilibrium position.

Amplitude (A) :- is the maximum displacement from equilibrium position.

Displacement (y) :- is position of a wave from equilibrium position at any time.

Example 3

How much heat energy is required to change a dog's ice cube from a solid at -10°C to steam at 110°C .

Solution

To raise the temperature of the ice to 0°C we need

$$\Delta Q_{\text{ice}} = m_{\text{ice}} C_{\text{ice}} \Delta T = 0.04 \text{ kg} \left(0.49 \frac{\text{kcal}}{\text{kg} \cdot ^\circ\text{C}} \right) 10^{\circ}\text{C}$$

To melt the ice we need $= \underline{\underline{0.196 \text{ kcal}}}$

$$\Delta Q_{\text{ice}} = m_{\text{ice}} L_{\text{ice}} = 0.04 \text{ kg} (80 \text{ kcal/kg}) = \underline{\underline{3.2 \text{ kcal}}}$$

To raise the temperature of 100°C we need

$$\Delta Q_{\text{ice}} = m_{\text{water}} C_{\text{water}} \Delta T = 0.04 \text{ kg} \left(1 \frac{\text{kcal}}{\text{kg} \cdot ^\circ\text{C}} \right) 100^{\circ}\text{C} = \underline{\underline{4 \text{ kcal}}}$$

To raise the temperature of the system to 110°C we need

$$\Delta Q_{\text{ice}} = m_{\text{system}} C_{\text{system}} \Delta T = 0.4 \text{ kg} (0.48 \text{ kcal}/(\text{kg} \cdot ^\circ\text{C})) [10^{\circ}\text{C}] = \underline{\underline{0.192 \text{ kcal}}}$$

To boil the water need

$$\Delta Q_L = m_{\text{water}} L_{\text{water}} = 0.04 \text{ kg} (540 \text{ kJ/kg}) = \underline{\underline{21.6 \text{ kJ}}}$$

Therefore total heat energy required is

$$\Delta Q = (0.96 + 3.2 + 4 + 21.6 + 0.192) \text{ kcal} = \underline{\underline{29.188 \text{ kcal}}}$$

Ex 2 If 90g of molten lead at 327.3°C is poured into a 80g Casting form made of iron and initially at 20°C . What is the final ~~for~~ temperature of the system?
Assume no energy lost to env't.

Soln The melting point of lead is 327.3°C . Assume the final temperature of the system is T .

* The amount of energy released by the lead as it solidifies is

$$\Delta Q_L = m_{\text{lead}} L_{\text{lead}} = 0.09 \text{ kg} (2.45 \times 10^4 \text{ J/kg}) = \underline{\underline{2205 \text{ J}}}$$

* The amount of energy released as it cools is

$$\Delta Q = m_{\text{lead}} C_{\text{lead}} \Delta T = 0.09 (128) (327.3 - T) = (11.52) (327.3 - T)$$

The energy is absorbed by the iron, for the iron

$$2205 + (11.52) (327.3 - T) = m_{\text{iron}} C_{\text{iron}} \Delta T = 0.3 (448) (T - 20)$$

$$5595.5 - (11.52)T = 134T - 2688$$

$$8663.5 = 145.52T$$

$$T = 59.5^{\circ}\text{C}$$

The Concept of Heat, Work and Internal energy

Heat, Symbol Q and unit joule(J) is spontaneous flow of energy into or out of a system caused by adiabatic temperature b/w system and surroundings.

Work, Symbol W and Unit joule(J), is non-spontaneous energy transfer into or out of a system due to force acting through a displacement.

Work takes many forms, moving a piston or stirring or running an electrical current through resistance.

Work is the non-spontaneous transfer of energy. Heat is microscopic form of energy transfer involving large no of particles.

A System Cannot possess heat or work. These two are energies that flow into or Out of a System.

Heat transfer obeys the law of Conservation of energy (if no heat is lost to surroundings)

$$Q_{\text{lost by hotter object}} = Q_{\text{gained by cooler object}}$$

Internal Energy, symbol U , is defined as the energy associated with the random, disordered motion of the microscopic components-atoms and molecules.

Specific Heat and Latent Heat

Specific heats:

Heat flowing into or out of a body (or system) changes the temperature of the body (or system) except during phase changes the temperature remains constant.

→ The quantity of heat Q required to change the temperature of the body of mass m by ΔT is proportional to both mass & ΔT

$$\text{Mathematically } Q \propto m \Delta T \rightarrow Q = mc \Delta T \quad \begin{matrix} \text{C - heat capacity} \\ \text{(or specific heat)} \end{matrix}$$

C - the amount of heat required to raise temperature of unit mass of any substance through a unit degree.

SI unit is J/kg.K or J/g.°C

→ The amount of heat required to change the temperature of n moles of a substance is $Q = nC\Delta T$

Latent heats:

Latent heat is the heat required per unit mass of a substance to produce a phase change at constant temperature.

→ the latent heat, Q_L , required to change the phase of "m" mass of a body at constant temperature is

Types of latent heats

$$Q_L = \pm mL$$

L - Specific latent heat required to change a phase of 1kg of a substance at a constant temperature.

1) Latent heat of fusion (L_f) is the heat absorbed or released when matter melts changing phase from solid to liquid form at constant temperature.

2) Latent heat of vaporization (L_v) is the heat absorbed or released when matter vaporizes changing phase from liquid to gas phase at constant temperature

Displacement, Velocity and acceleration in SHM

① Displacement $\rightarrow X = A \sin \omega t$

$$\textcircled{a} \quad \text{Velocity} = wA \cos(\omega t)$$

$$\textcircled{1} \text{ Acceleration} = -\omega^2 A \sin(\omega t) = -\omega^2 X$$

* Maximum Velocity occurs at equilibrium position with $x = 0$.

* Maximum acceleration occurs at $X = \pm A$; $a_{max} = \omega^2 A$

$$V_{max} = \omega A$$

$$a_{\max} = \omega^2 A$$

Example

An object oscillates with SHM along x-axis. Its position varies with time according to equation $x = (4.00) \text{ m} \cos(\pi t + \frac{\pi}{4})$ where t is in seconds and angles in radians.

- a) Determine A , f , and T of motion
 - b) Calculate \vec{V} , & \vec{a} at any time.
 - c) Using results of part b, determine position, Velocity & \vec{a} at $t = 15$
 - d) determine maximum Speed and maximum acceleration of object.

Solution

Gülen

Given $x = (4.00) \text{ m} \cos(\omega t + \frac{\pi}{4})$ with the general eqn of Simple HM

$$a) A = 4 \text{ m}, \omega = \underline{\underline{\pi}}_{\text{rad}}, x(t) = A \cos(\omega t + \phi)$$

$$T = \frac{1}{f} = \frac{1}{0.5} = 2 \text{ sec}$$

$$b) \vec{V} = \frac{dx}{dt} = \frac{d(4m \cos(\omega t + \frac{\pi}{4}))}{dt} = -(4\pi)m \sin(\omega t + \frac{\pi}{4})$$

$$a = \frac{dv}{dt} = - (4\pi)^2 m/s^2 \cos(\pi t + \frac{\pi}{4})$$

c) at $t = 1.5$ sec

$$x(t) = 4 \cos(\pi t + \frac{\pi}{4}) = 4 \cos(\pi(u) + \frac{\pi}{4})$$

$$V(t) = -4\pi \sin(\pi t + \frac{\pi}{4}) = 4 \cos(\pi t + \frac{\pi}{4}) = -2.83 \text{ m}$$

$$= -4x \sin \frac{5\pi}{4} = 8.89 \text{ m/s}$$

$$a(t) = - (4\pi)^2 \cos(\pi(t) + \pi_0)$$

$$d) V_{max} = \omega A = 12.56 \text{ m/s}$$

$$a_{\max} = \omega^2 A = 39.4 \text{ m/s}^2$$

Amplitude (A) is the maximum displacement of the oscillator from the equilibrium position.

Example: On average a human heart is found to beat 75 times in a minute. Calculate its frequency and period.

$$\Rightarrow f = \frac{75}{1 \text{ minute}} = \frac{75}{60 \text{ s}} = \underline{\underline{1.25 \text{ Hz}}}$$

$$T = \frac{1}{f} = \frac{1}{1.25 \text{ Hz}} = \underline{\underline{0.8 \text{ sec}}}$$

→ Simple harmonic motion is a special type of oscillatory motion caused by a restoring force which obeys Hooke's law.

In SHM acceleration

a) is always directly proportional in size but opposite in direction to its displacement (x).

A block of mass m , attached to one end of a spring, of constant k and oscillating in a horizontal frictionless floor, is example of SHM.



$$F_s = -kx$$

The minus (-) sign shows the force is always acting opposite to the displacement and always tries to restore the block back to its equilibrium position.

Newton's 2nd law $F_s = ma$

$$ma = -kx \rightarrow a = -\left(\frac{k}{m}\right)x = \underline{\underline{-\omega^2 x}}$$

* K is Constant of proportionality called the Spring Constant or Stiffness factor and ω is angular frequency of oscillator.

Characteristics of SHM

- 1) The amplitude A is constant
- 2) The frequency and period are independent of Amplitude
3. The fluctuating quantity can be expressed in terms of Sinusoidal function of a Single frequency.

For SHM to occur

- there must be a stable equilibrium position
- there must be no dissipation of energy
- the acceleration is proportional to displacement & opposite in direction.